

# **Segmentation of Image Sequences by Mathematical Morphology**

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# Outline



- ↓ **Introduction**
- ↓ **Connected Filters**
- ↓ **Watershed**
- ↓ **Beucher-Meyer Segmentation Paradigm**
- ↓ **Aperture Operators**
- ↓ **Automatic Design of Morphological Operators**
- ↓ **Methodology and Applications**

# Introduction



- ↖ **Digital video edition is an important task nowadays.**
- ↖ **Some usual areas of applications are:**
  - ↖ **Advertisement**
  - ↖ **Special effects on movies**
  - ↖ **Re-mastering of old movies**
  - ↖ **Rotoscoping**

# Introduction



- ↖ **Computational tools are being used to help this task.**
- ↖ **Some applications are not easy, for instance:**
  - composing*** (i.e. segmentation and mixing of video sequences.)
- ↖ **A known technique is called *Chroma Keying*.**

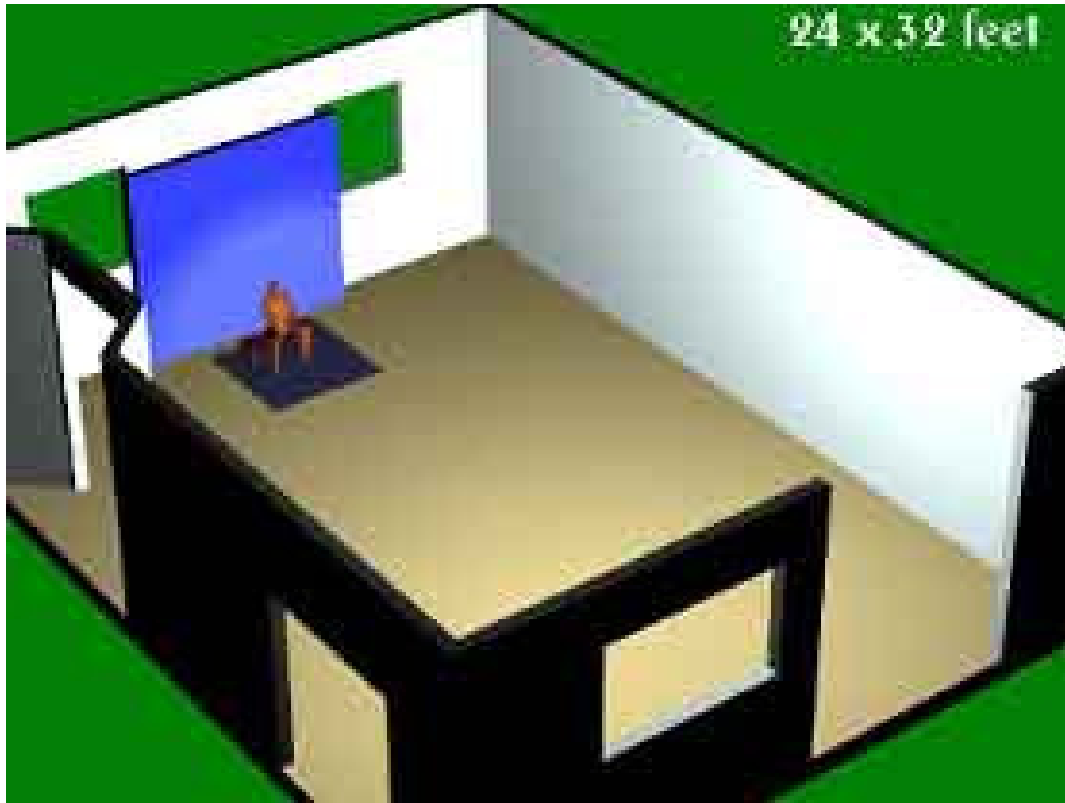
# Introduction



- ↖ **Some special cares have to be taken, though:**
  - ↖ **The scene has to be photographed in front of a bright, colored background.**
  - ↖ **Objects to be substituted have to be covered by a colored (green, blue, etc) cloth.**
  - ↖ **The image processing technique applied in the chroma keying is classical **pattern recognition**, using pixel color intensities as attributes.**

# Chroma Keying

↖ Photo Studio applications



# Chroma Keying

↖ Video sequence applications

Forrest Gump and John Lennon being interviewed “together”



# Rotoscoping



- ↖ **Tracking live actions to create animation or an animated matte is usually called **Rotoscoping****
- ↖ **It is applied mainly for short sequences**
- ↖ **The tracking is usually done manually with the help of a pointing device**



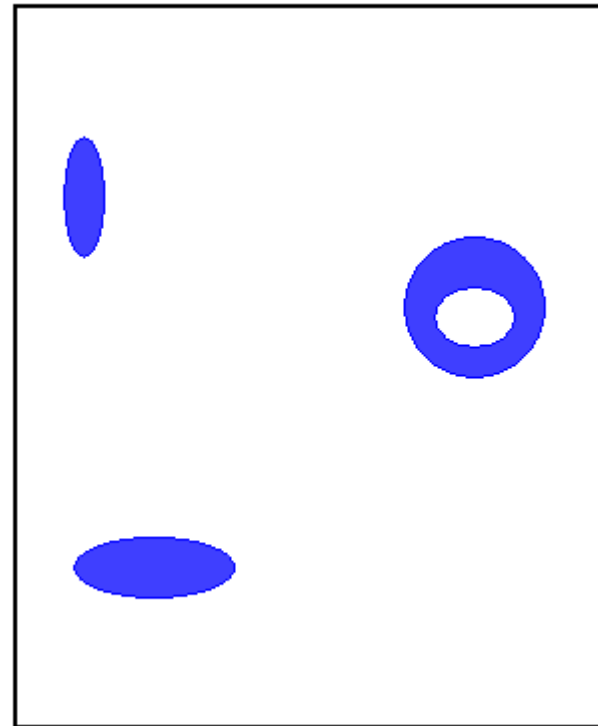
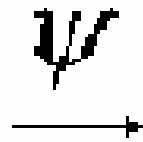
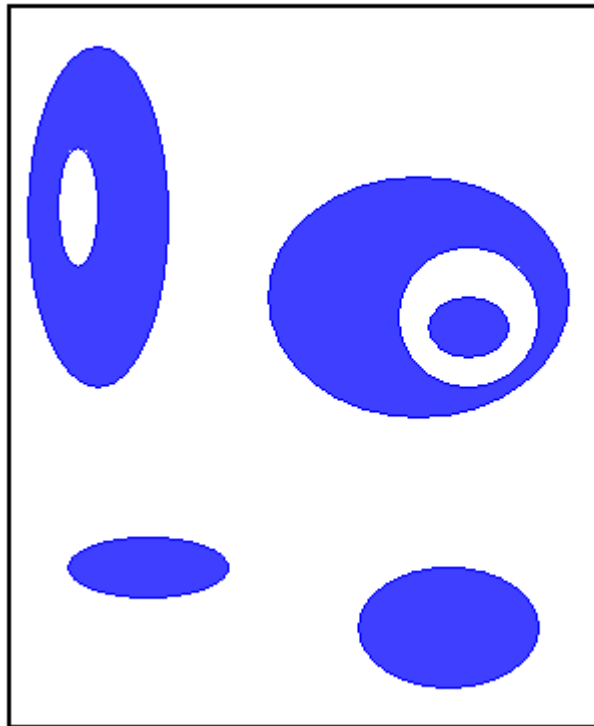
# Connected Filters



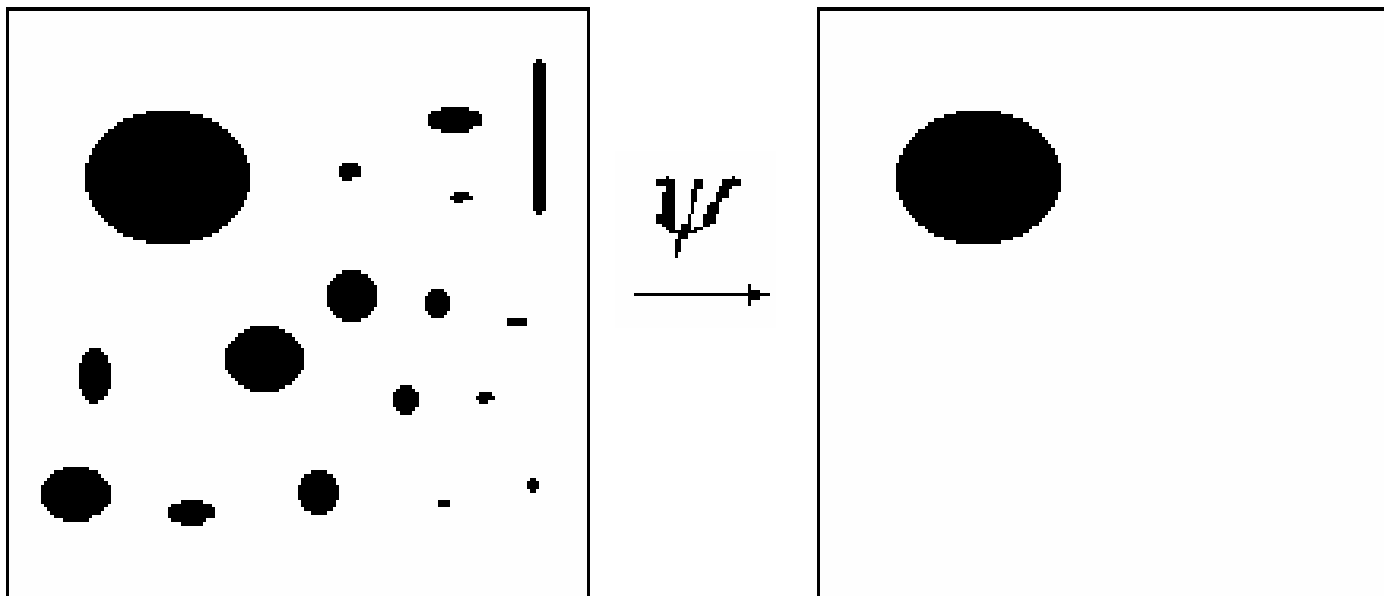
- ↖ **Connected filters** are operators that act on the level of the **flat zones** of an image, not on the level of the pixels.
- ↖ They **can not** introduce new discontinuities, only **suppress** existing ones.
- ↖ They are well suited for image segmentation because they preserve the important desired borders.

# Connected Filters

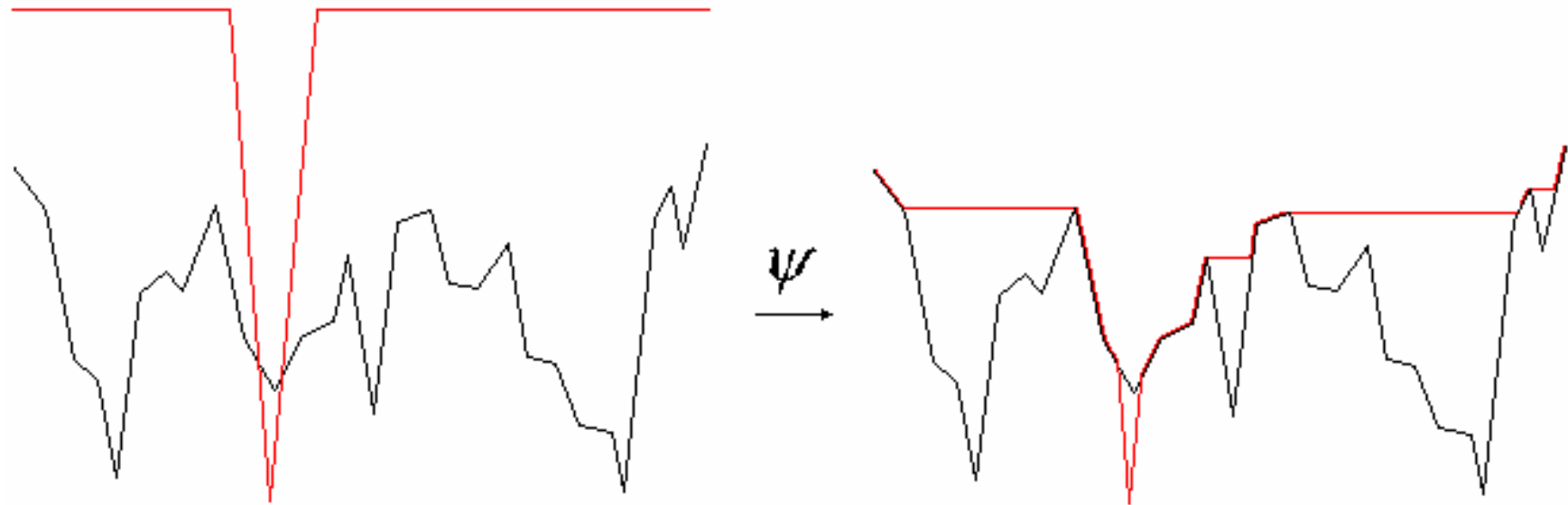
Planning



# Areaopen Filter



# Homotopy Filter

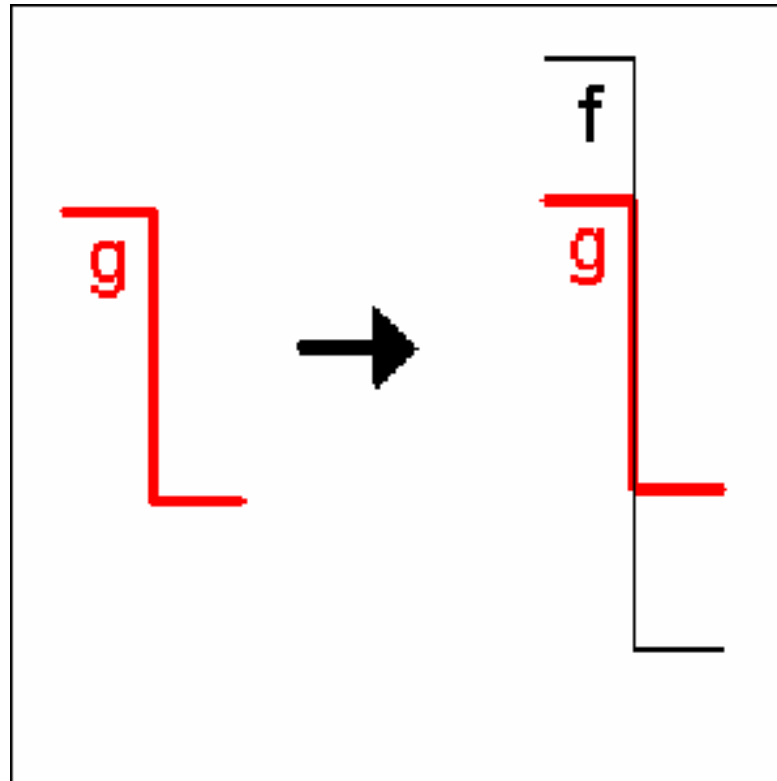


# Levelings

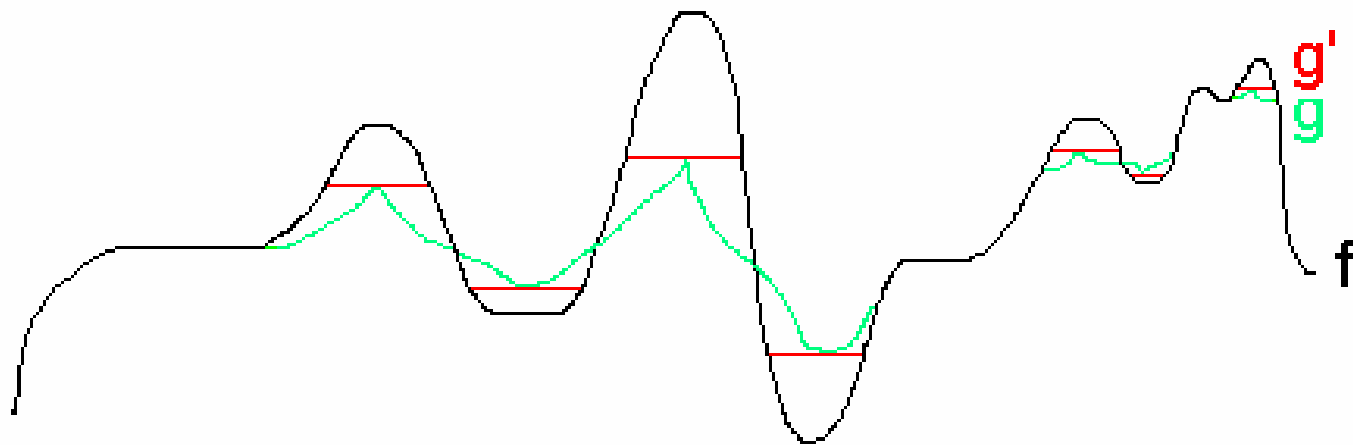


- ↖ **Levelings** is a good methodology to simplify the image before segmentation
- ↖ It creates and enlarges homogeneous (quasi-flat) zones
- ↖ It can simplify the image before automatic design of operators

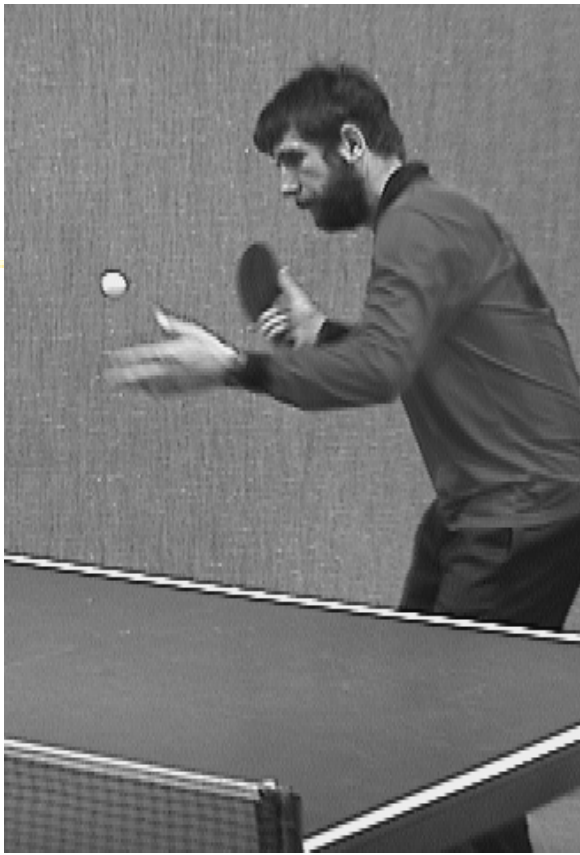
# Levelings



# Levelings



# Levelings



**Original**



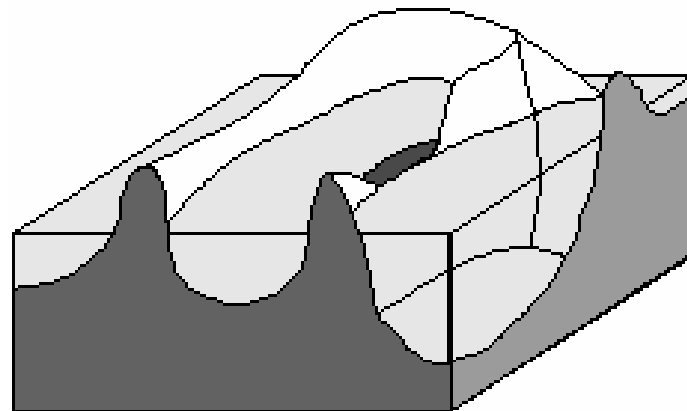
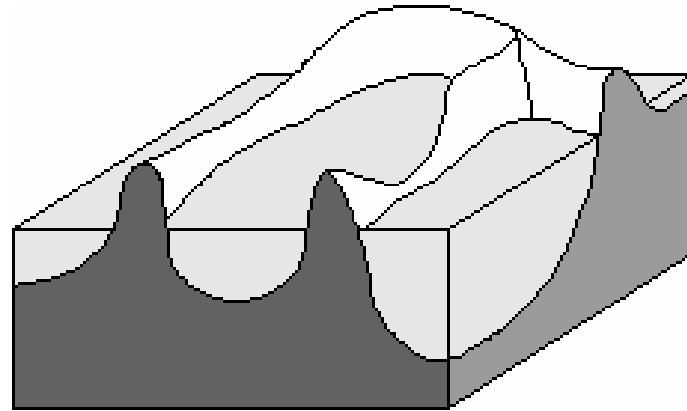
**Marker**



**Result**

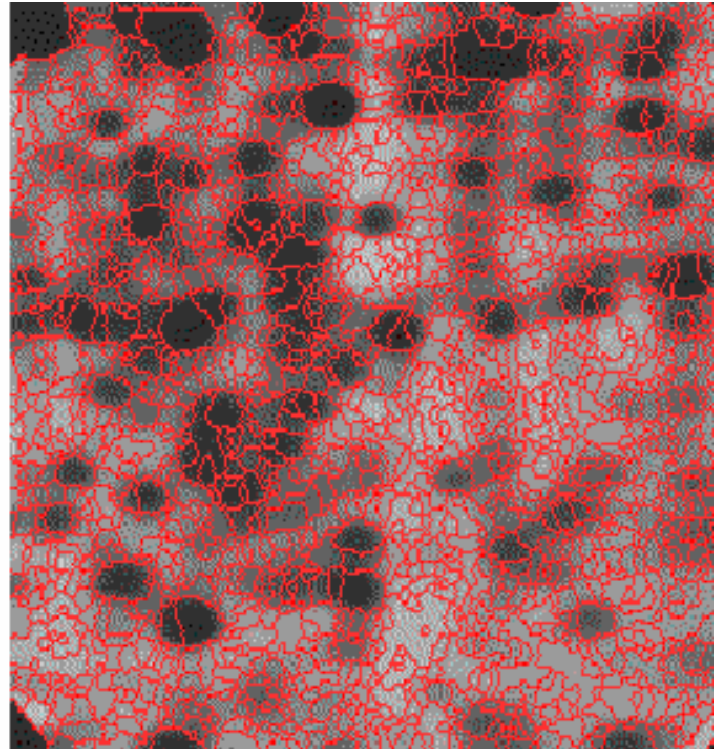
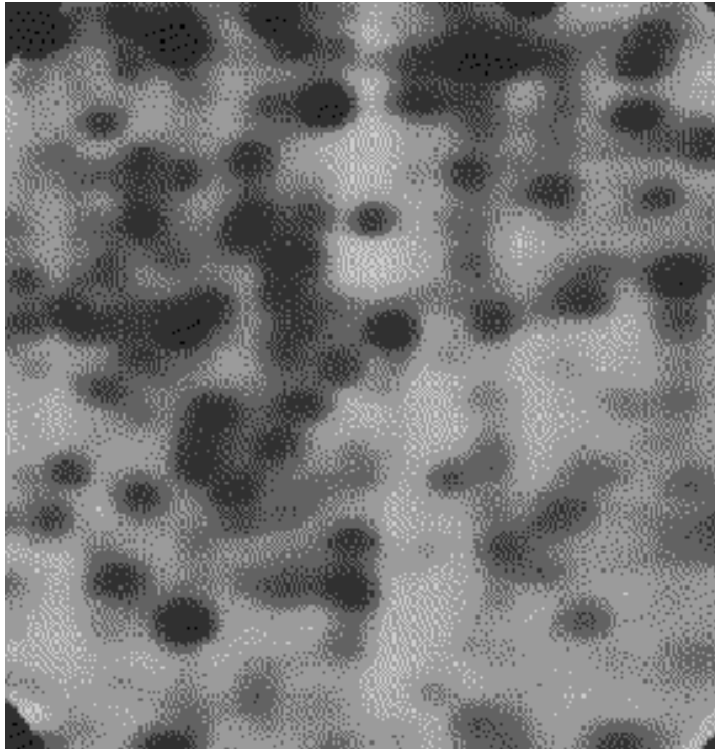


# Watershed



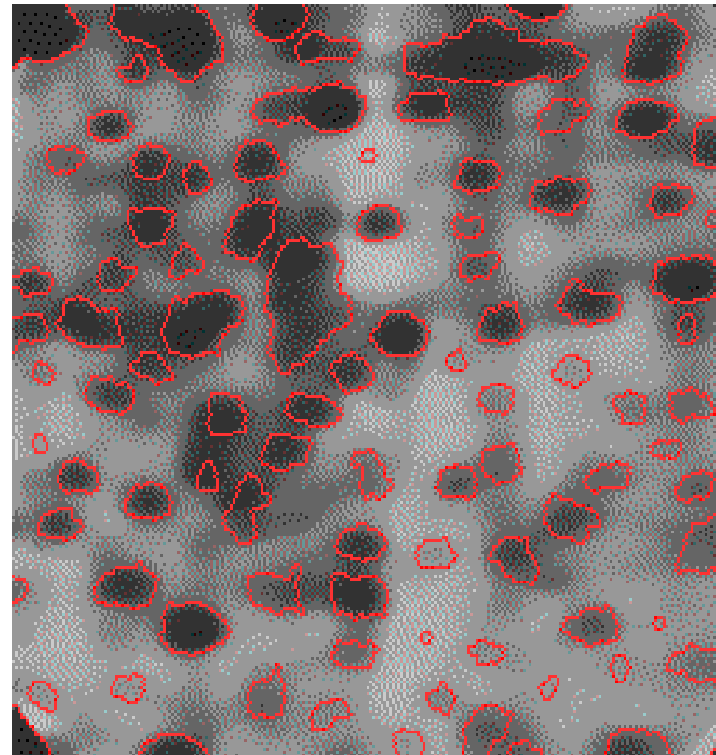
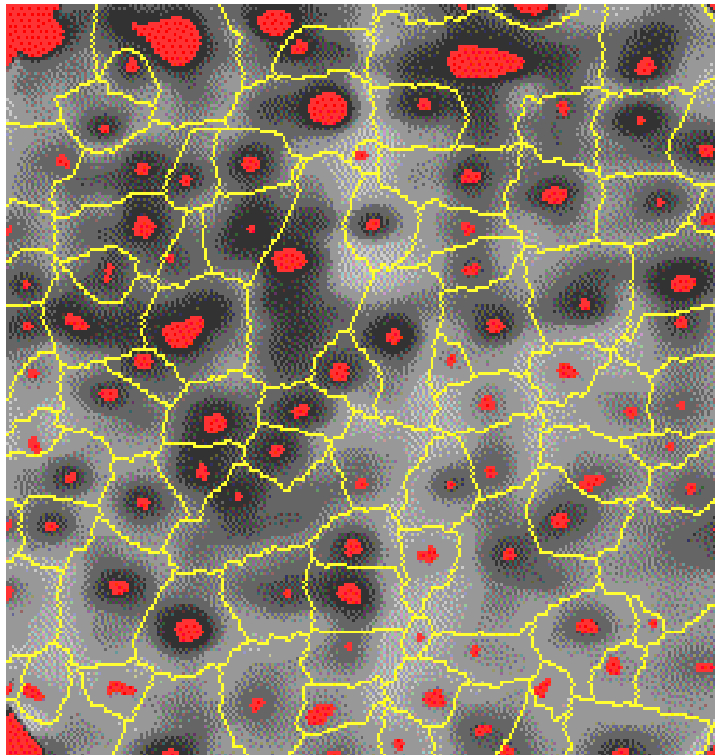
# Oversegmentation

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# Markers

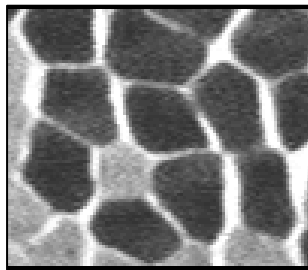
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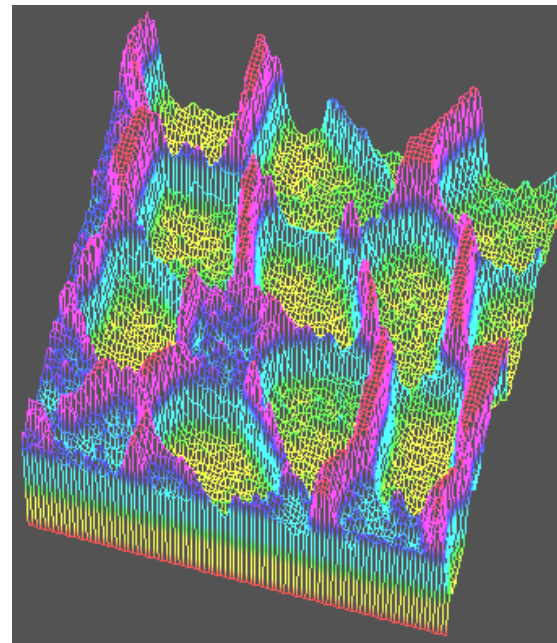
# Beucher-Meyer Paradigm

- ↖ A powerful segmentation method to find the **borders** of specified objects in an image.

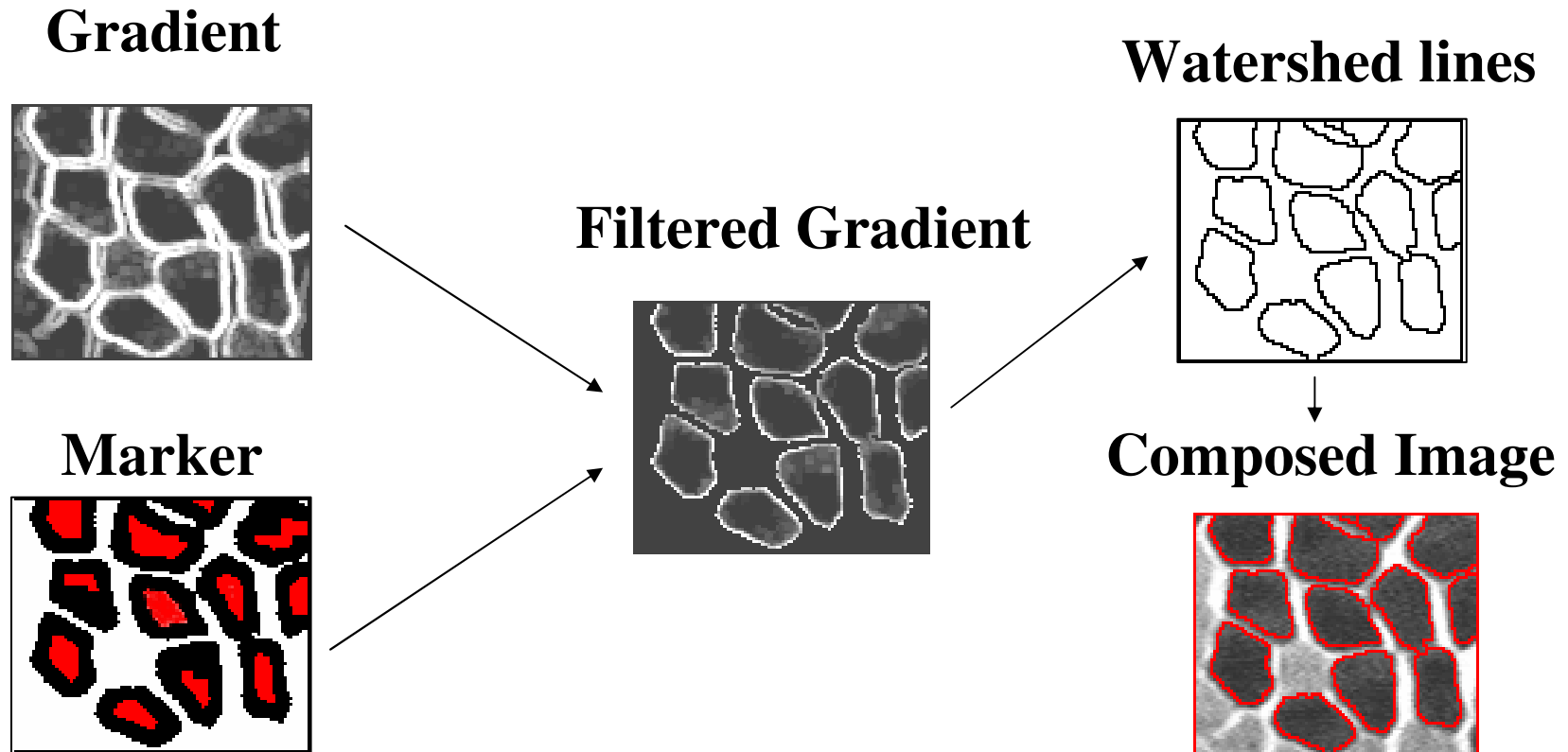
2D



3D



# Beucher-Meyer Paradigm



# Design of Image Operators



- ↖ A **fundamental problem** in Mathematical Morphology is the design of function operators
- ↖ An **approach** for operators design is statistical optimization in a space of operators
- ↖ In the **optimization**, it is fixed a family of useful operators that have a standard representation
- ↖ The **complexity** of the optimization depends on the size of the family of operators considered

# Design of Image Operators

- ↖ In the **binary** case, the family of W-operators is usually considered
- ↖ The family of **binary** W-operators has  $2^{2^{|W|}}$
- ↖ In the **gray-scale** case, the family of W-operators is also usually considered
- ↖ The family of **gray-scale** W-operators has  $l^m{|W|}$
- ↖ In **ordinary** applications  $l=m=256$

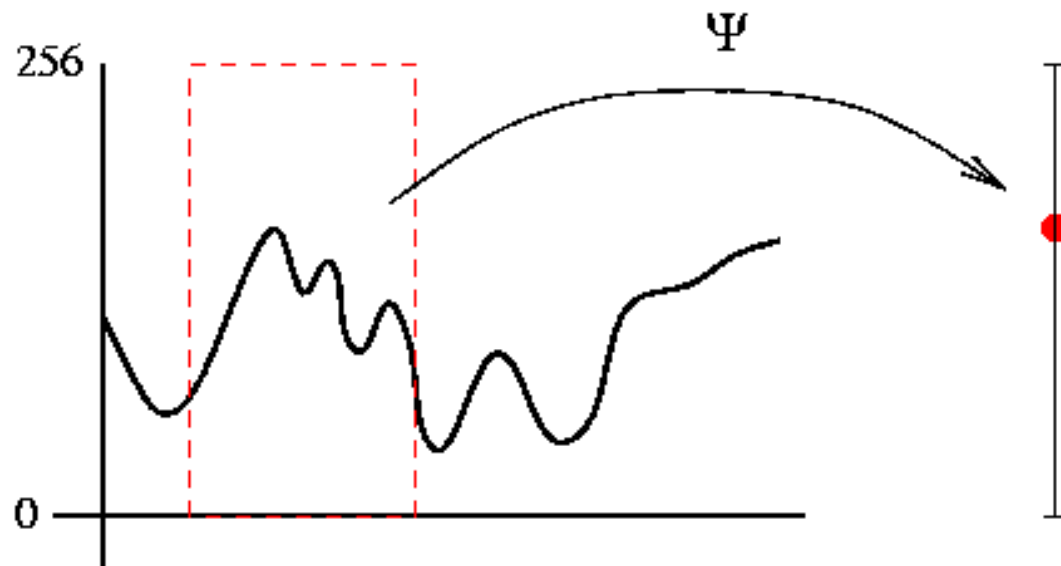
# Design of Aperture Operators

- ↖ The family of **Aperture operators** depends on a spatial window  **$W$**  and a gray-scale window  **$K$**
- ↖ The **family** of aperture filters has  $k^{|W|}$
- ↖ The **complexity** of the optimization problem is controlled by  $k$  and  $|W|$
- ↖ The values of  $k$  and  $|W|$  depends on the problem:  $k=3, 5, 7, \dots$  and  $|W| = 9, 25, 49, \dots$



# Characteristic Functions

$$\psi: L^W \rightarrow M$$



# Design of Aperture Operators

## K-characteristic functions

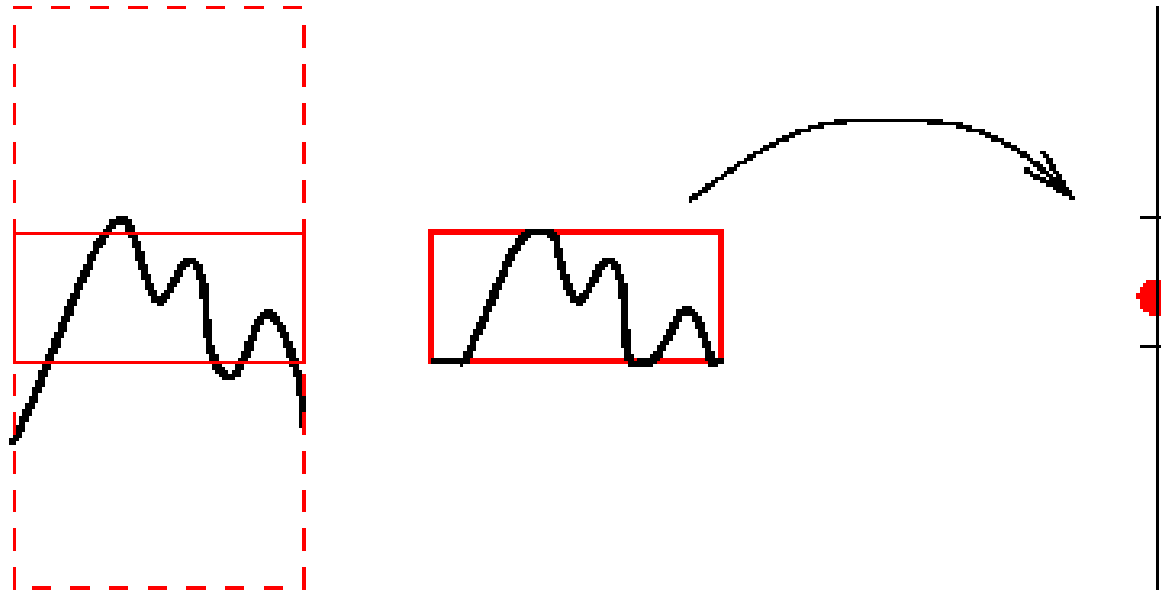
↖ **Gray-scale translation:**  $(u + y)(z) = u(z) + y$

↖ **Gray-scale window:**  $\left\{ -\frac{k-1}{2}, \dots, -1, 0, 1, \dots, \frac{k-1}{2} \right\}$

# Design of Aperture Filters

## Windowing in the space and range

$$(u / K_y)(z) = \cap \left\{ \cup \left\{ -\frac{k-1}{2}, u(z) - y \right\}, \frac{k-1}{2} \right\}$$



# Design of Aperture Operators

↖ **gray-scale t. i.:**  $\psi(u + y) = \psi(u) + y$

↖ **locally defined in K:**  $\psi(u) = u(o) + \beta_{u(o)}(u / K_{u(o)})$

↖ **representation:**  $\psi(u) = u(o) + \beta_{\psi}(u / K_{u(o)})$

$\beta_\psi$ 

2	-2	1	2	2	2
1	-2	1	2	2	2
0	-2	1	2	2	2
-1	-2	1	1	1	1
-2	-2	-2	-2	-2	-2
	-2	-1	0	1	2

 $\psi$  $u(o)$  $\beta_\psi$ 

14	12	13	14	15	16		14	10	11	12	13	14		14	2	2	2	2	2
13	12	13	14	15	15		13	10	11	12	13	14		13	2	2	2	2	1
12	12	13	14	14	12	=	12	10	11	12	13	14	+	12	2	2	2	1	-2
11	12	13	13	11	12		11	10	11	12	13	14		11	2	2	1	-2	-2
10	12	12	10	11	12		10	10	11	12	13	14		10	2	1	-2	-2	-2
	10	11	12	13	14			10	11	12	13	14			10	11	12	13	14

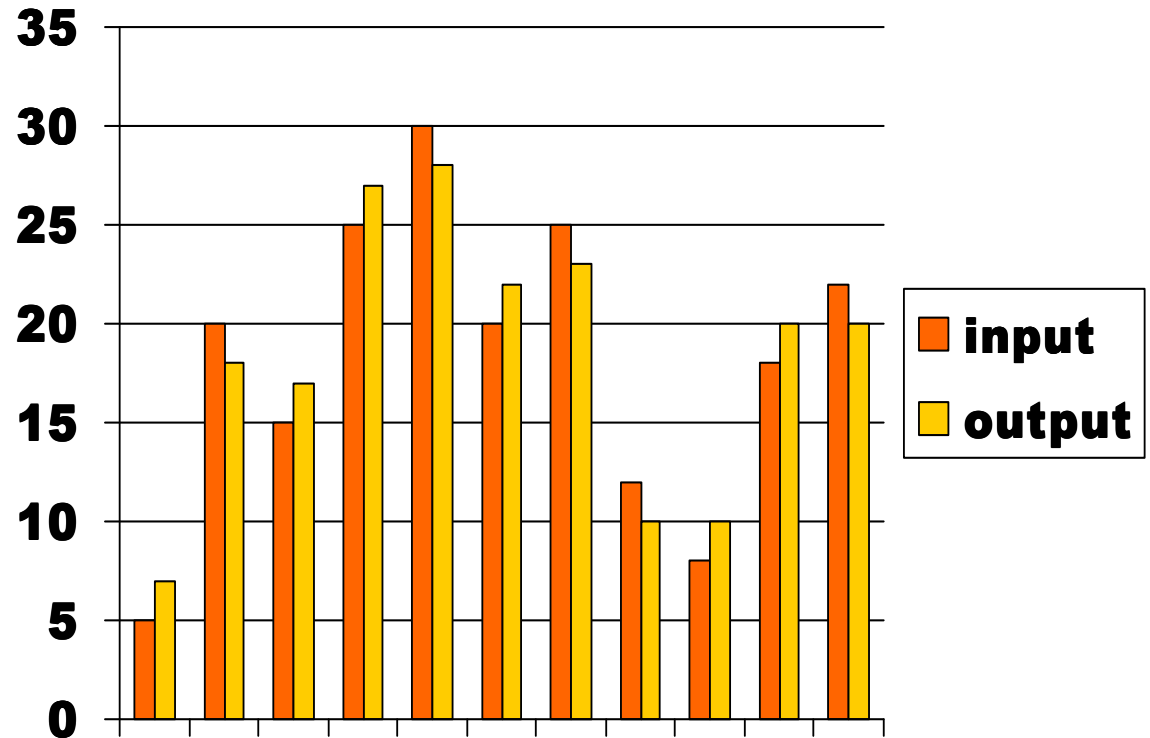
# Aperture Operators

W   $K = \{-2, -1, 0, 1, 2\}$

$\beta_\psi$

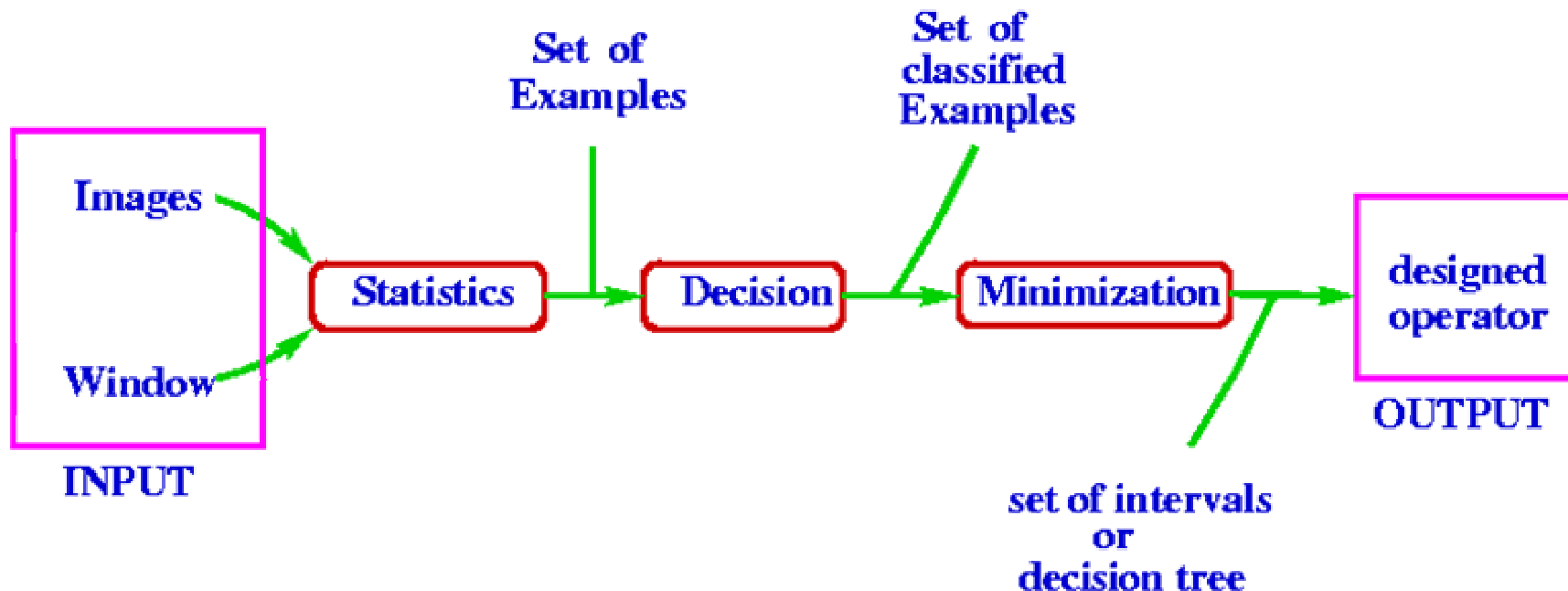
2	-2	1	2	2	2
1	-2	1	2	2	2
0	-2	1	2	2	2
-1	-2	1	1	1	1
-2	-2	-2	-2	-2	-2
	-2	-1	0	1	2

$\Psi$



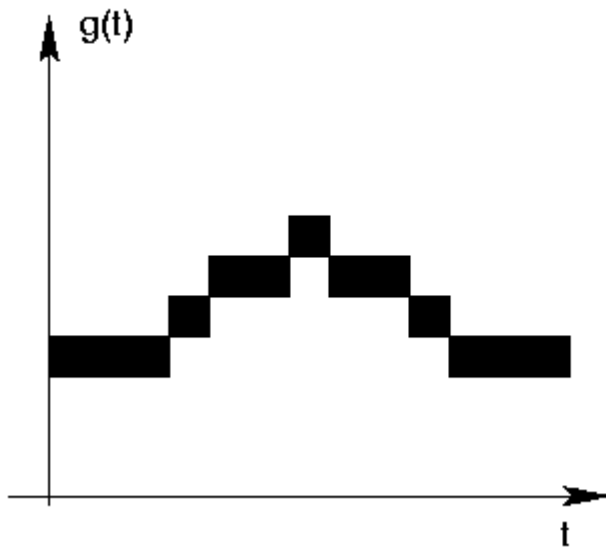
# Design of Aperture Operators

## Learning System

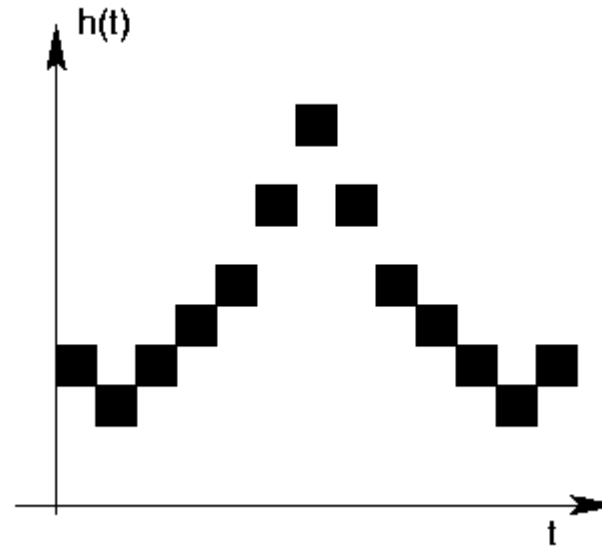


# Design of Aperture Operators

**Observed**



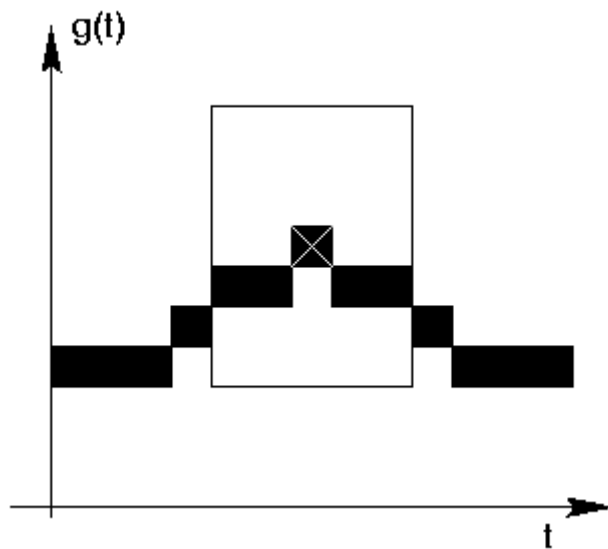
**Ideal**



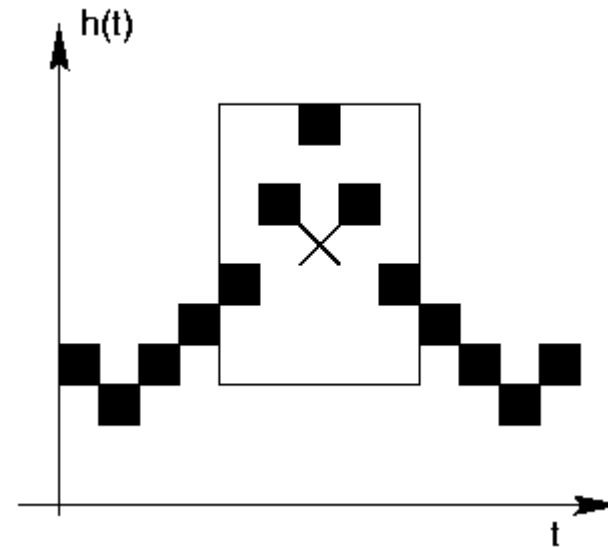


# Design of Aperture Operators

Windowing observed

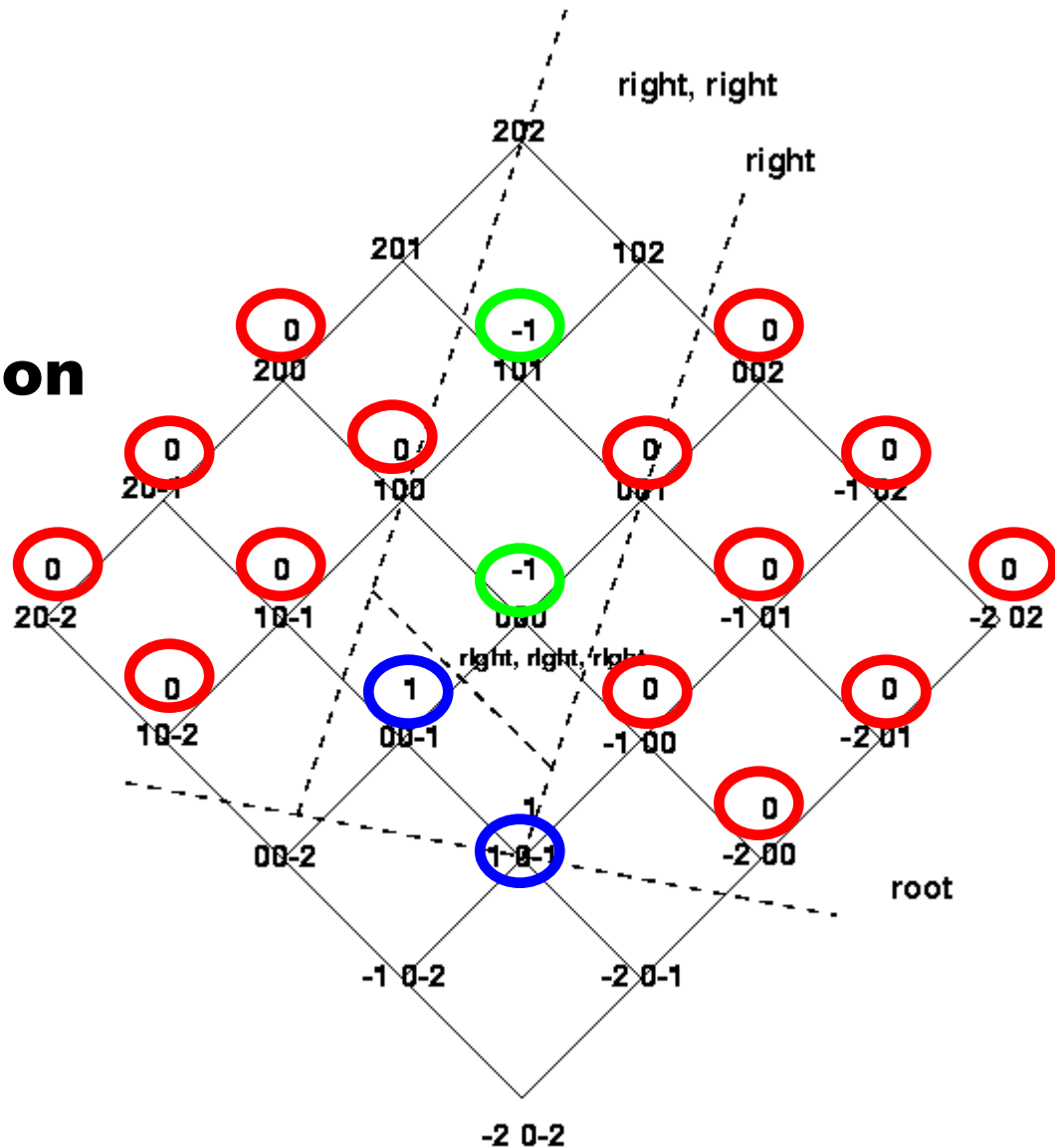


The center of the window  
seen at the same  
position in the Ideal



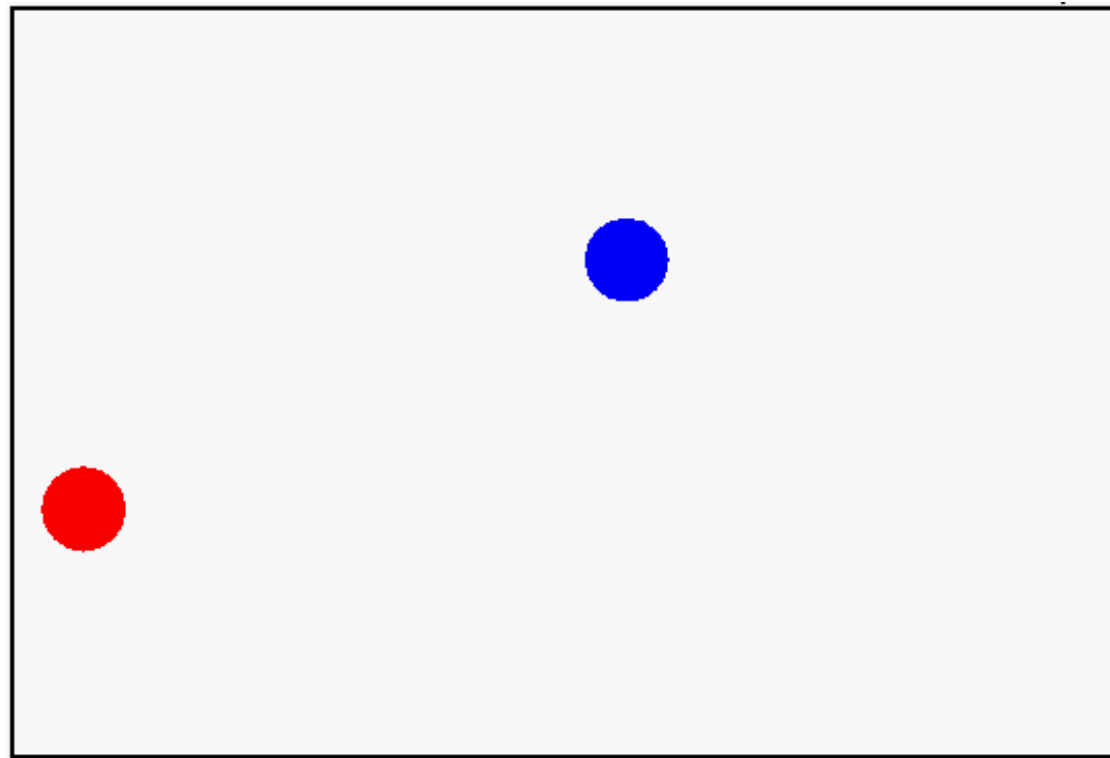
# One representation of Aperture Operators

Lattice representation of the kernel of the operator



# The proposed technique

**Automatic design of morphological operators  
for Motion Segmentation**



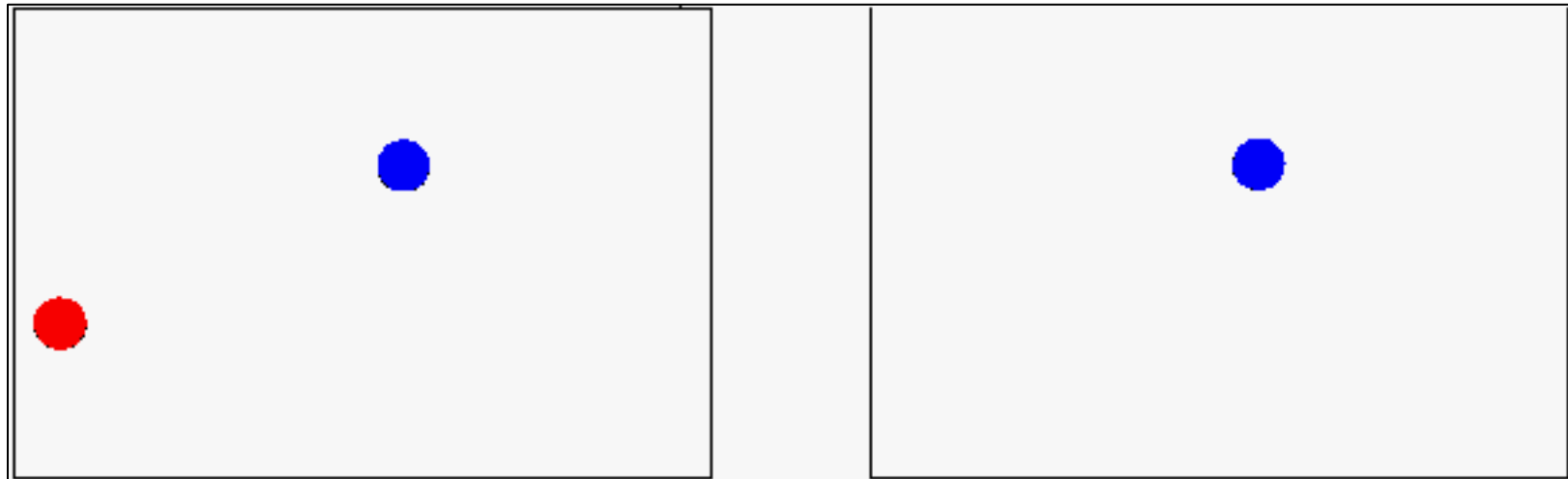
# The proposed technique

Some frames are segmented and used to train an operator

Observed

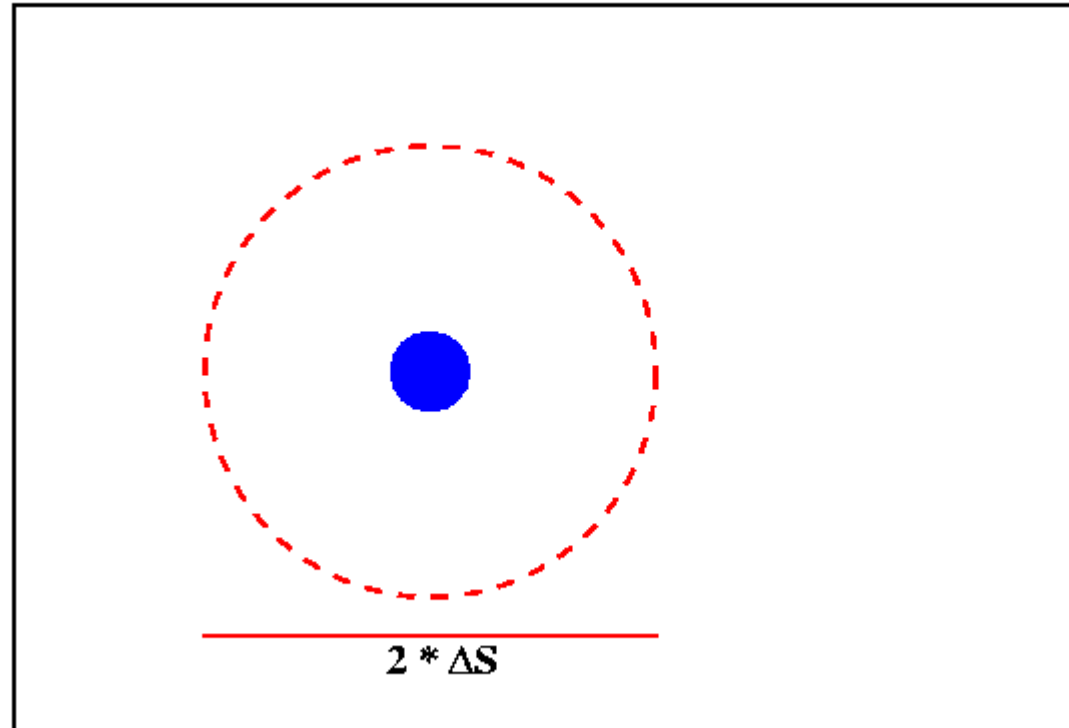


Ideal



# Applying the proposed technique

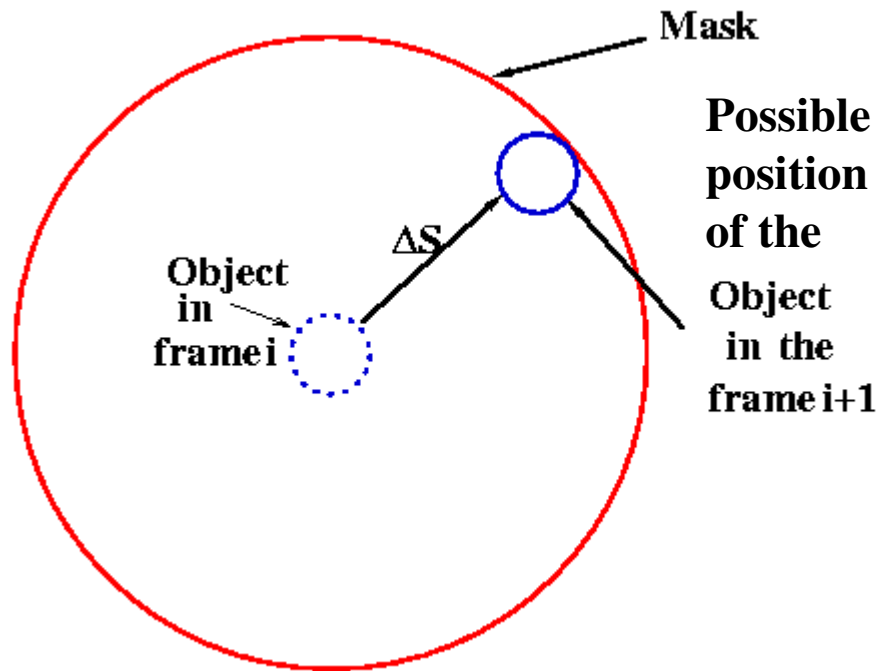
The first frame of the sequence is segmented manually



The speed of the object is also a parameter

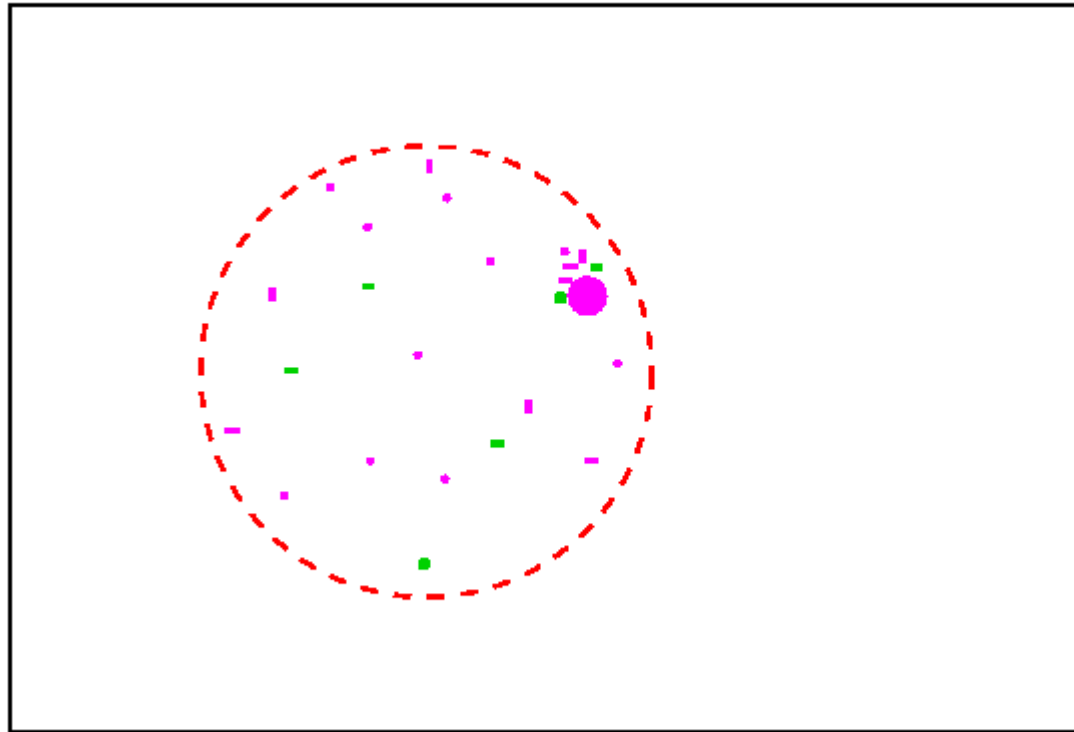
# Applying the proposed technique

The position of the object in the first frame plus its speed determine the application **mask** for the next frame



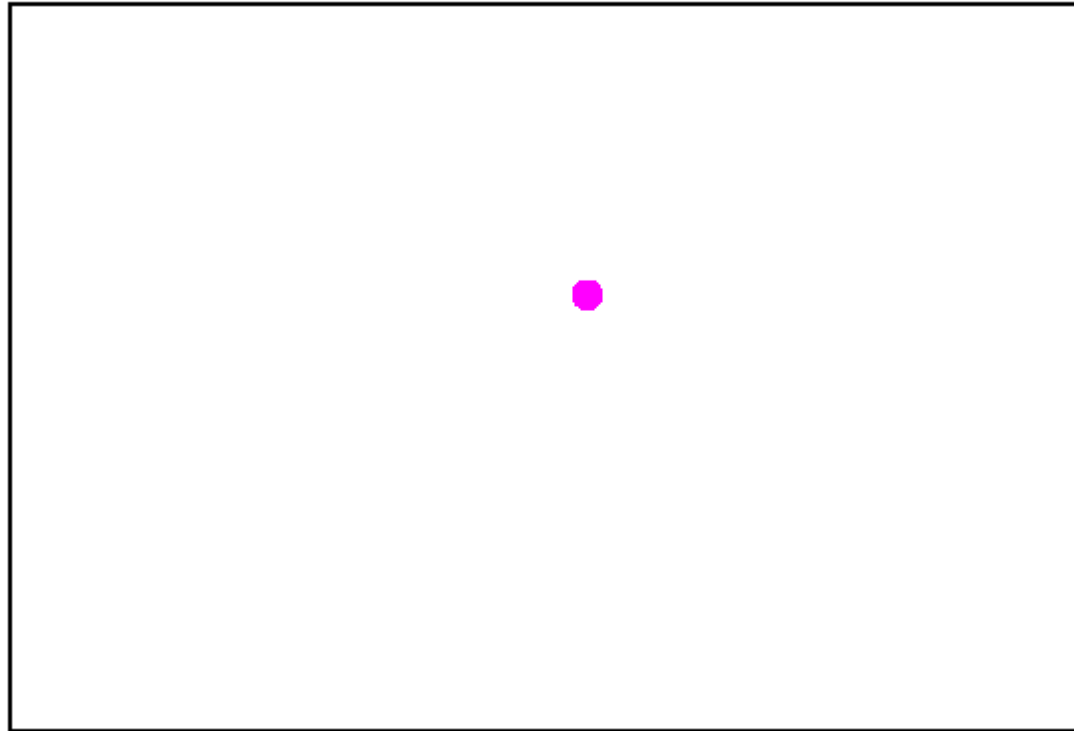
# Applying the proposed technique

The operator is applied inside the application mask



# Applying the proposed technique

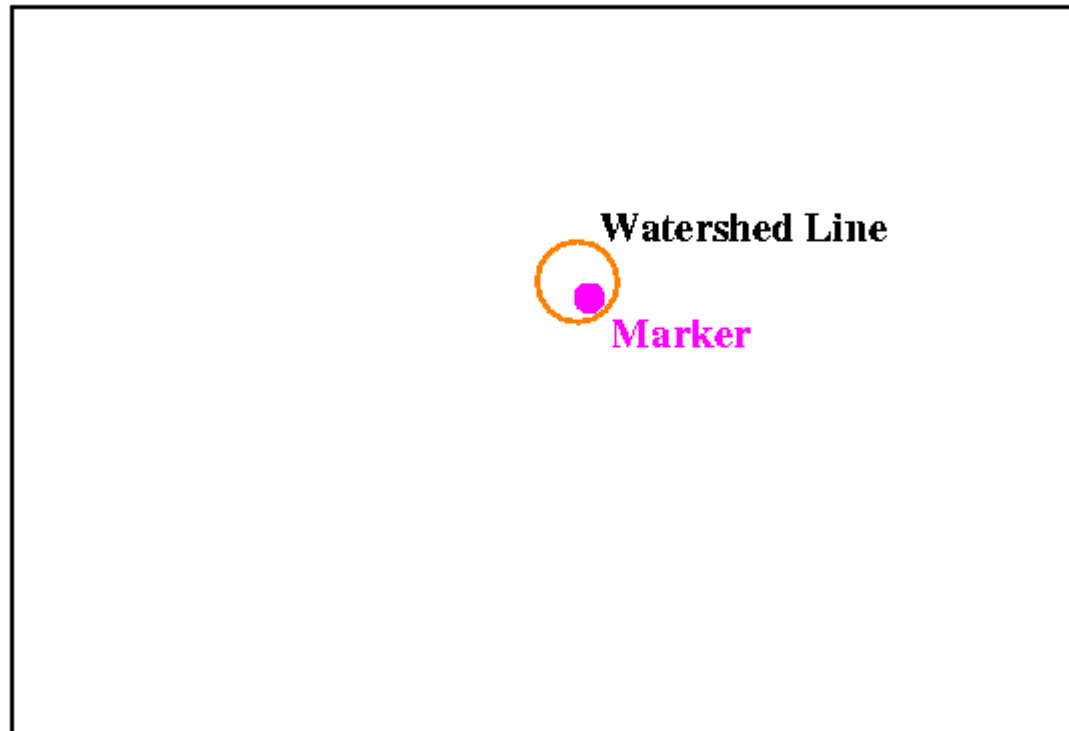
The result is filtered (area opening)





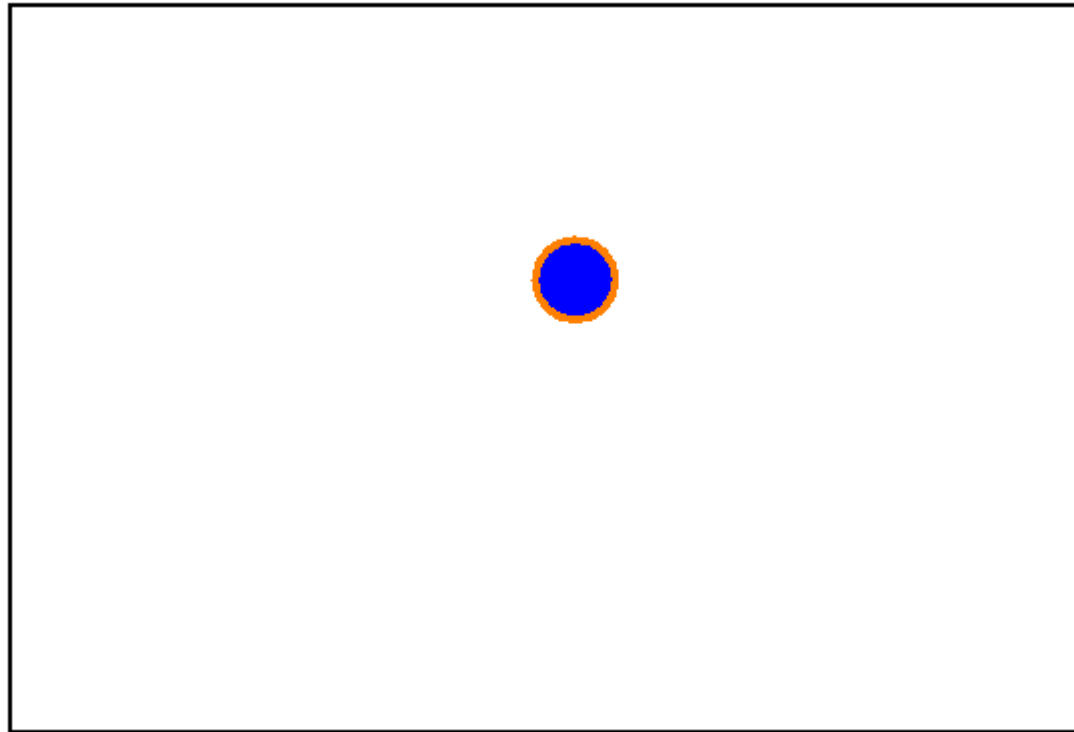
# The proposed technique

Beucher-Meyer paradigm is applied



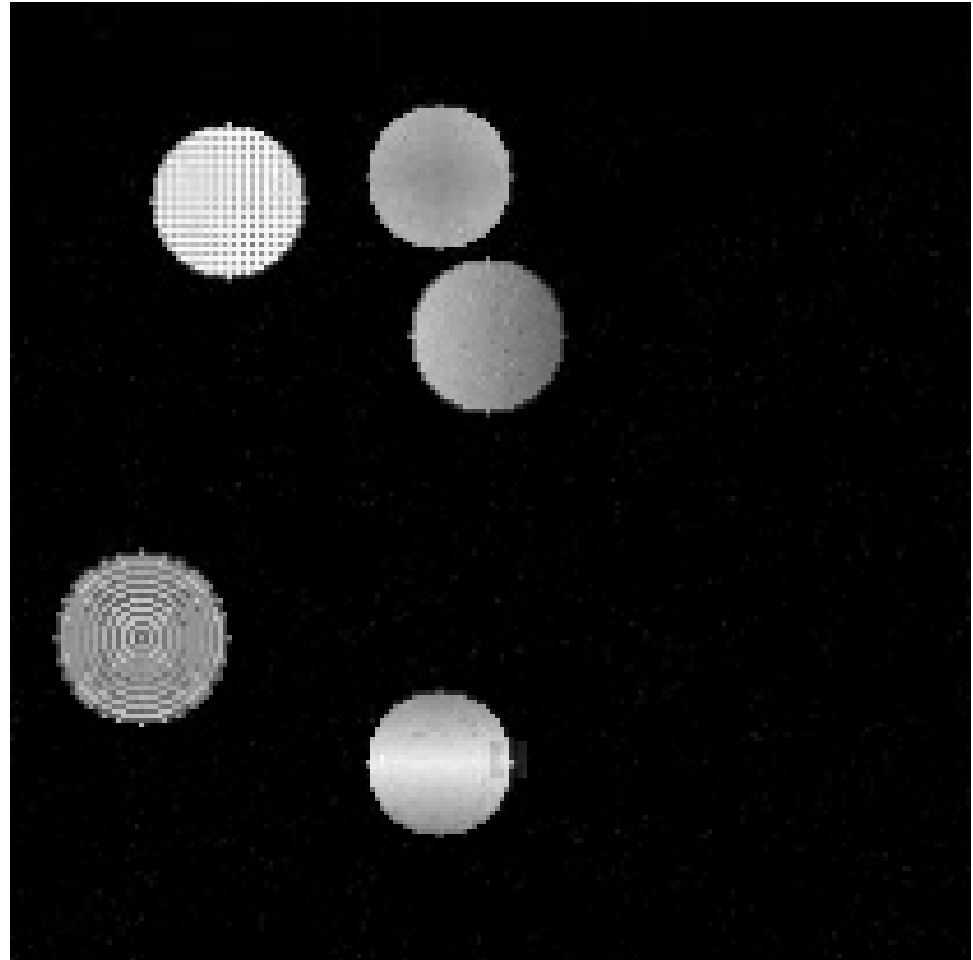
# The proposed technique

The segmented object can be substituted or analysed



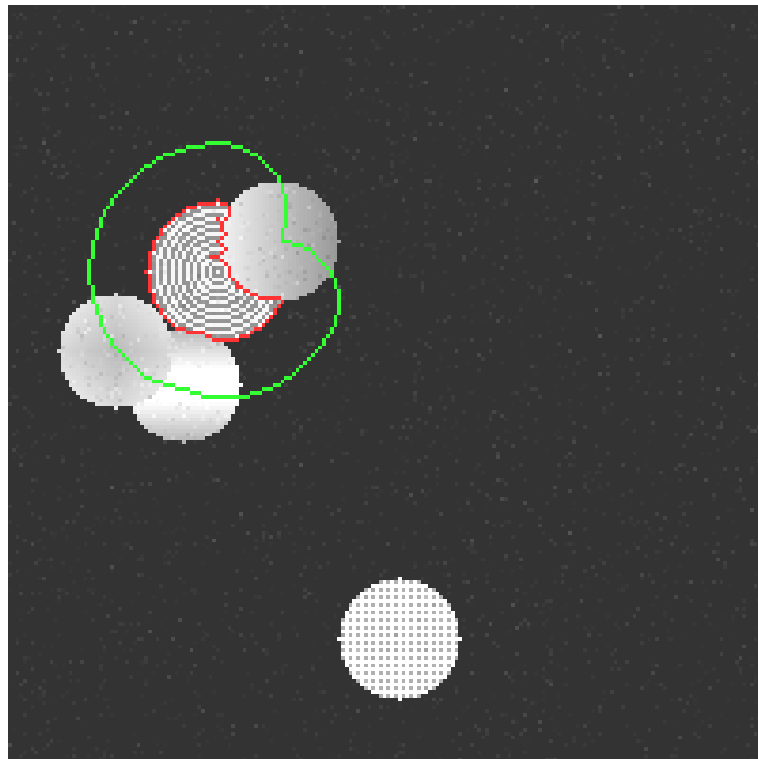
# Applications - simulation

## Tracking disks

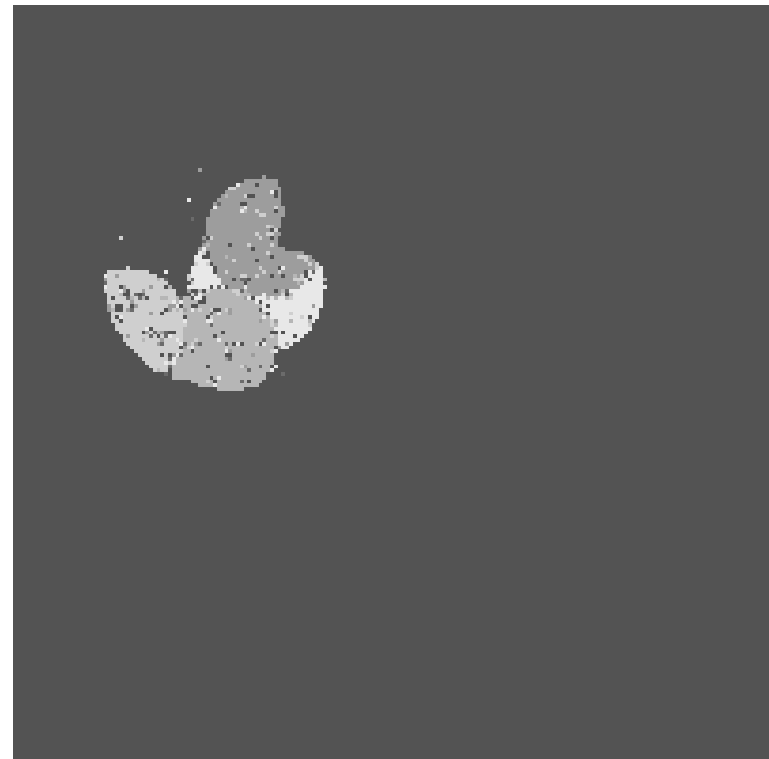


# Applications

**Mask**

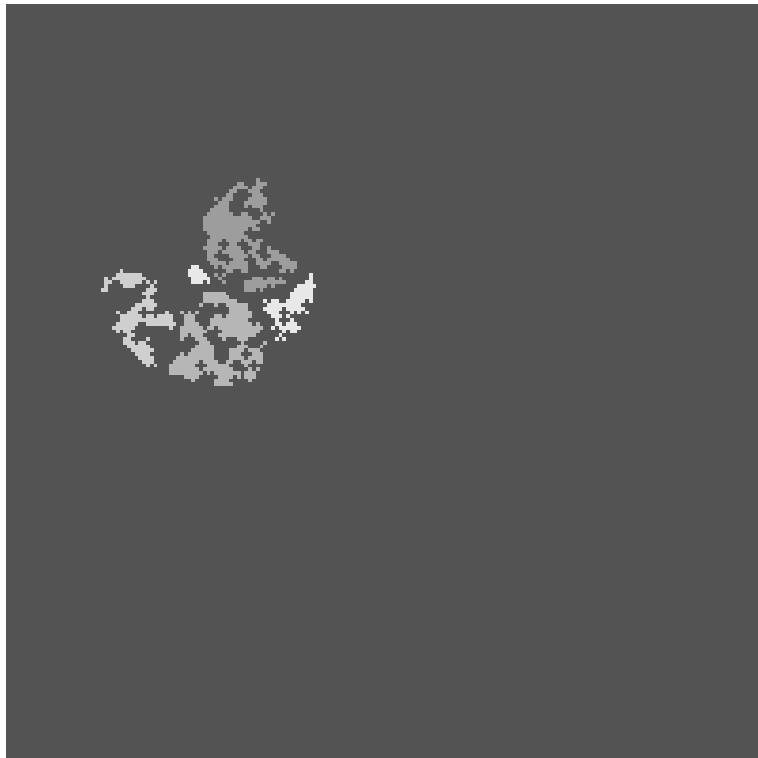


**Result of the application**

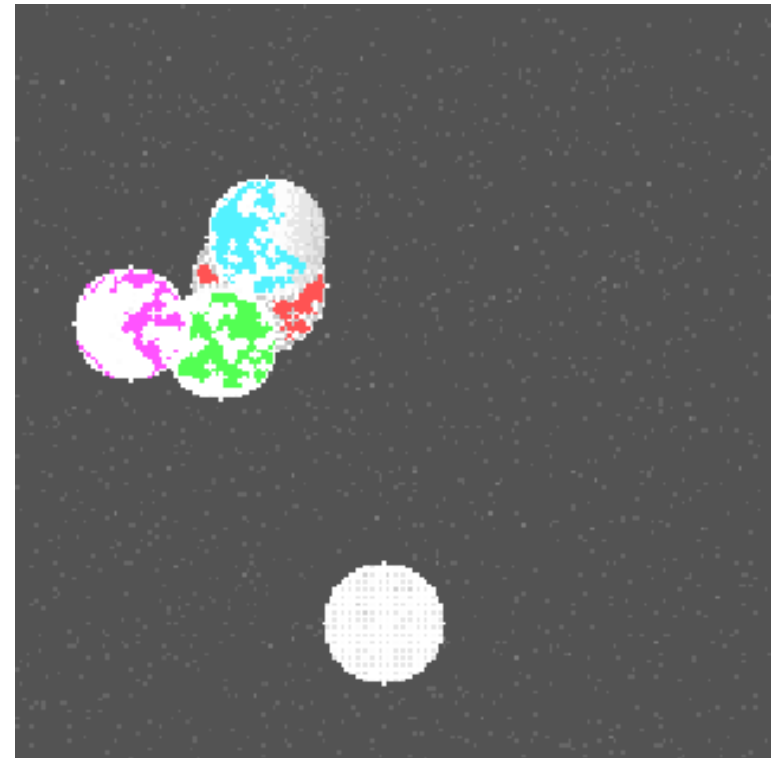


# Applications

**Result of the connected filter**



**Composition**



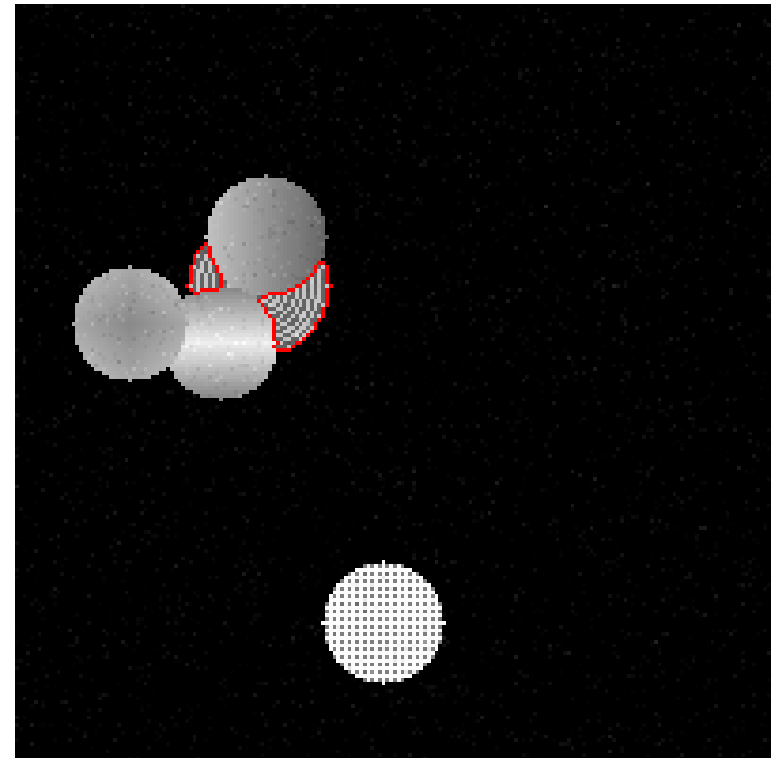
# Applications

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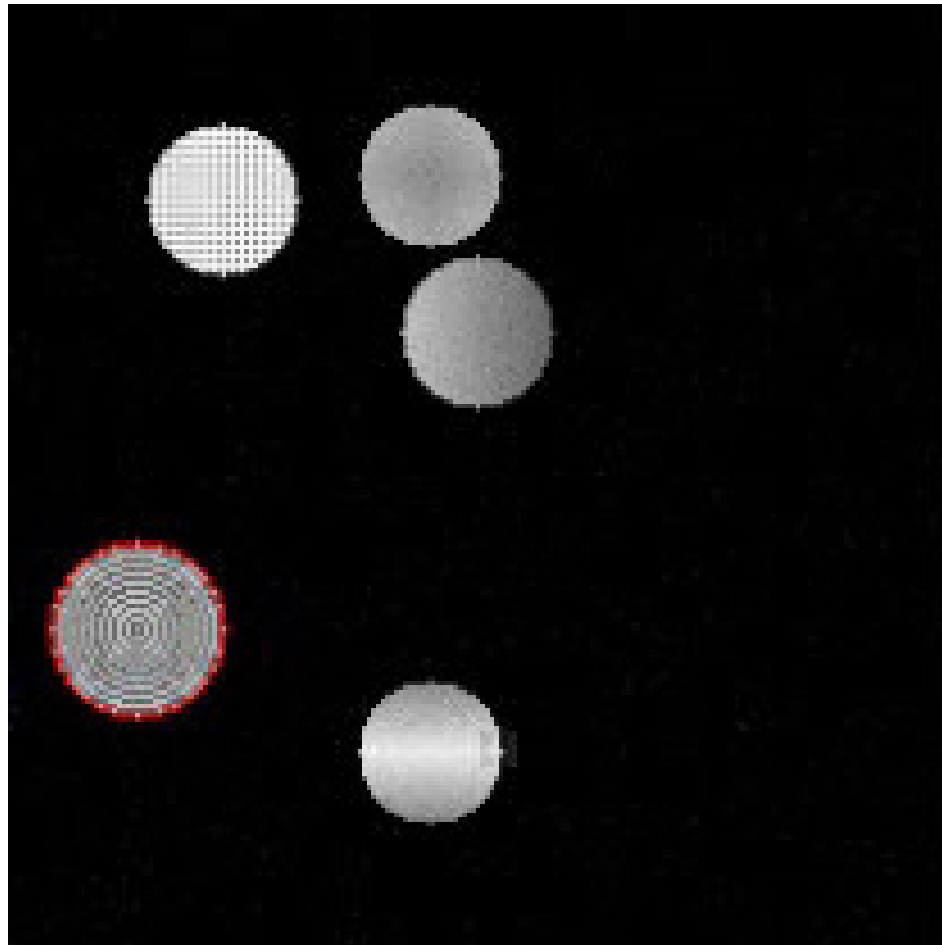
**Watershed regions**



**Composed Result**



# Applications - tracking one disk



# Applications

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## Tracking a table tennis ball

Two problems have been explored in this sequence

- Track the ball
- Track the racquet





# Applications - **Tracking the ball**



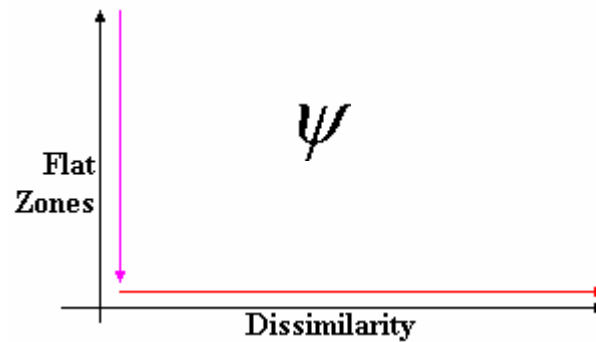
# Applications - Tracking the racquet



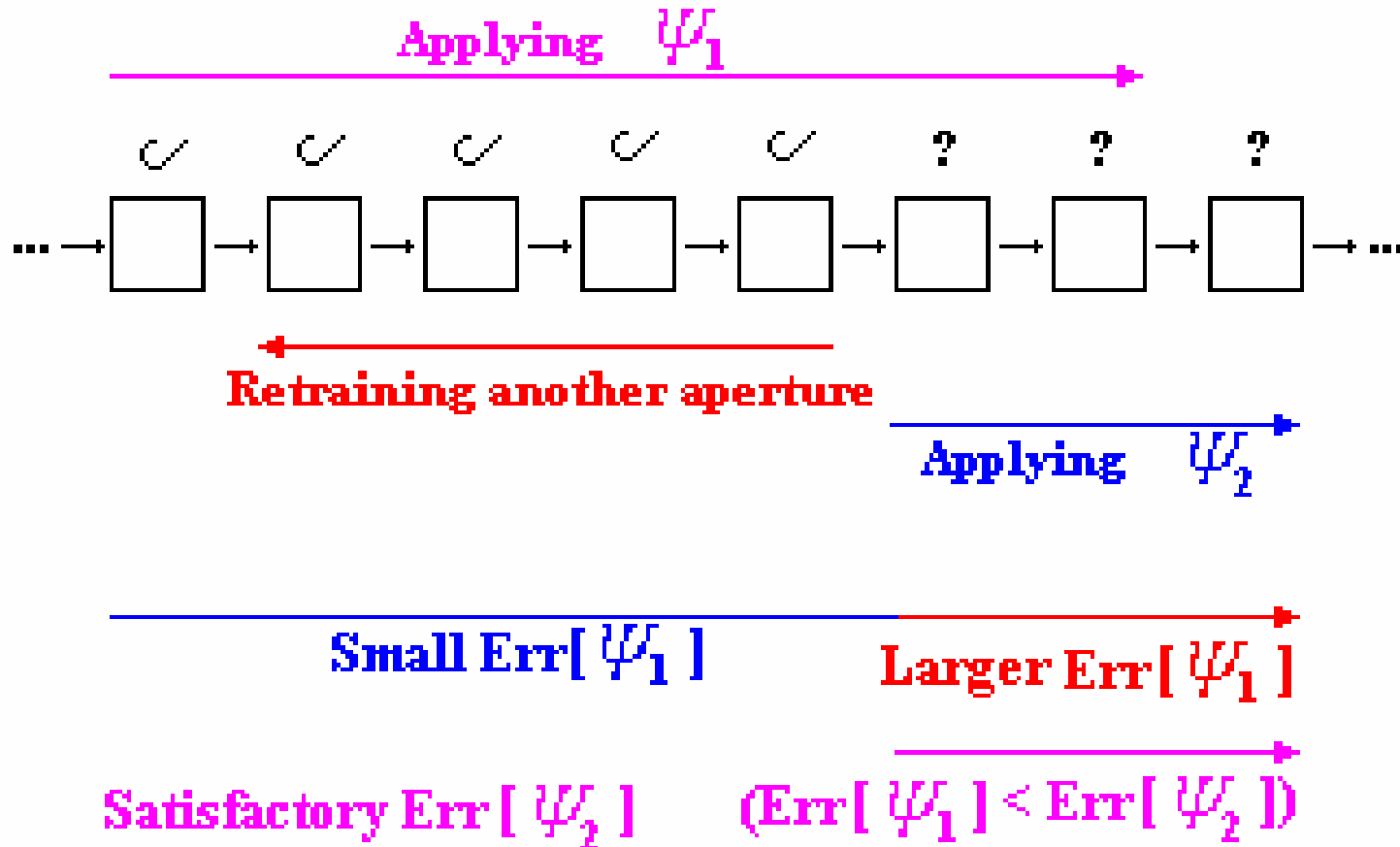
# Future Research



**Design of Aperture Operators for Image Simplification by  
Connected Filters**

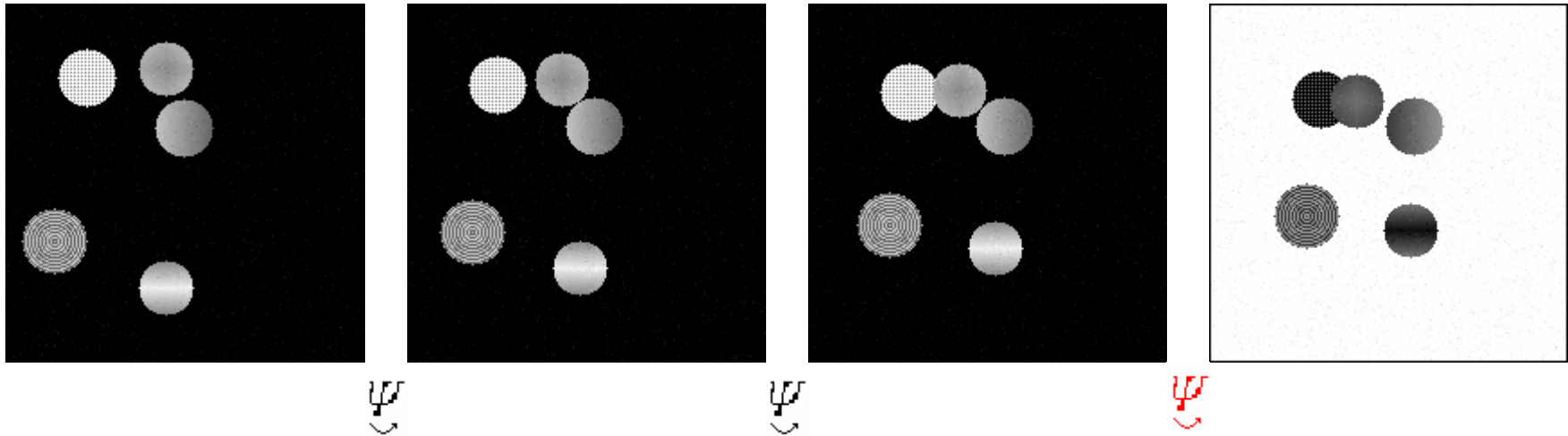


# Future Research



Design of Adaptive Filters

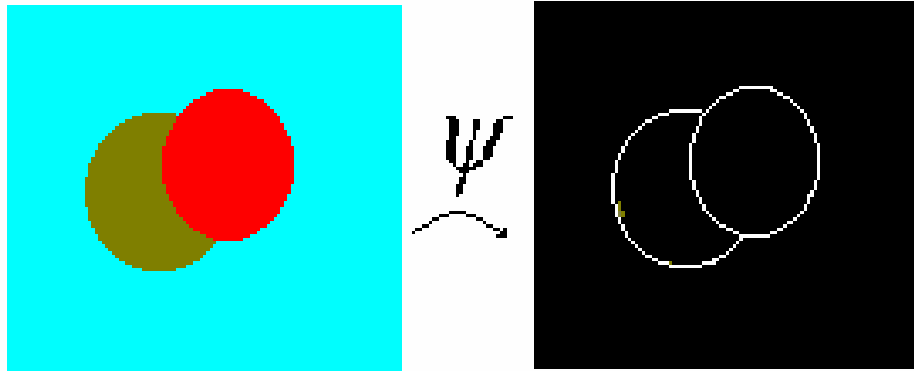
# Future Research



**Detection of Abrupt Changes in the Scene**

# Future Research

## Design of Aperture Operators for Color Image









$N(x)$ : neighbourhood of  $x$

$d(a, b)$ : a metric

$$\nabla G(x) = \max\{d(x, y) : y \in N(x)\}$$

# Future Research

X	$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$	...
						...
						...
						...
						...
						...
						...
⋮	⋮	⋮	⋮	⋮	⋮	⋮
⋮	⋮	⋮	⋮	⋮	⋮	⋮
⋮	⋮	⋮	⋮	⋮	⋮	⋮

**Design of Aperture Operators for Color Image**

# Correlation

