

# Some Applications of Aperture Filters

**Roberto Hirata Jr.\***

**Edward R. Dougherty\*\***

**Junior Barrera\***

**\* Instituto de Matemática e Estatística - USP**

**\*\* Department of Electrical Engineering - TAMU**

# Outline

- **Introduction**
- **Aperture Operators**
- **Statistical Design of Image Operators**
- **Apertures for Deblurring**
- **Resolution Enhancement**
- **Markers for Segmentation**

# Introduction

- A **fundamental** problem in Mathematical Morphology is the design of function operators
- An **approach** for operators design is statistical optimization in a space of operators
- In the **optimization**, it is fixed a family of useful operators that have a standard representation
- The **complexity** of the optimization depends on the size of the family of operators considered

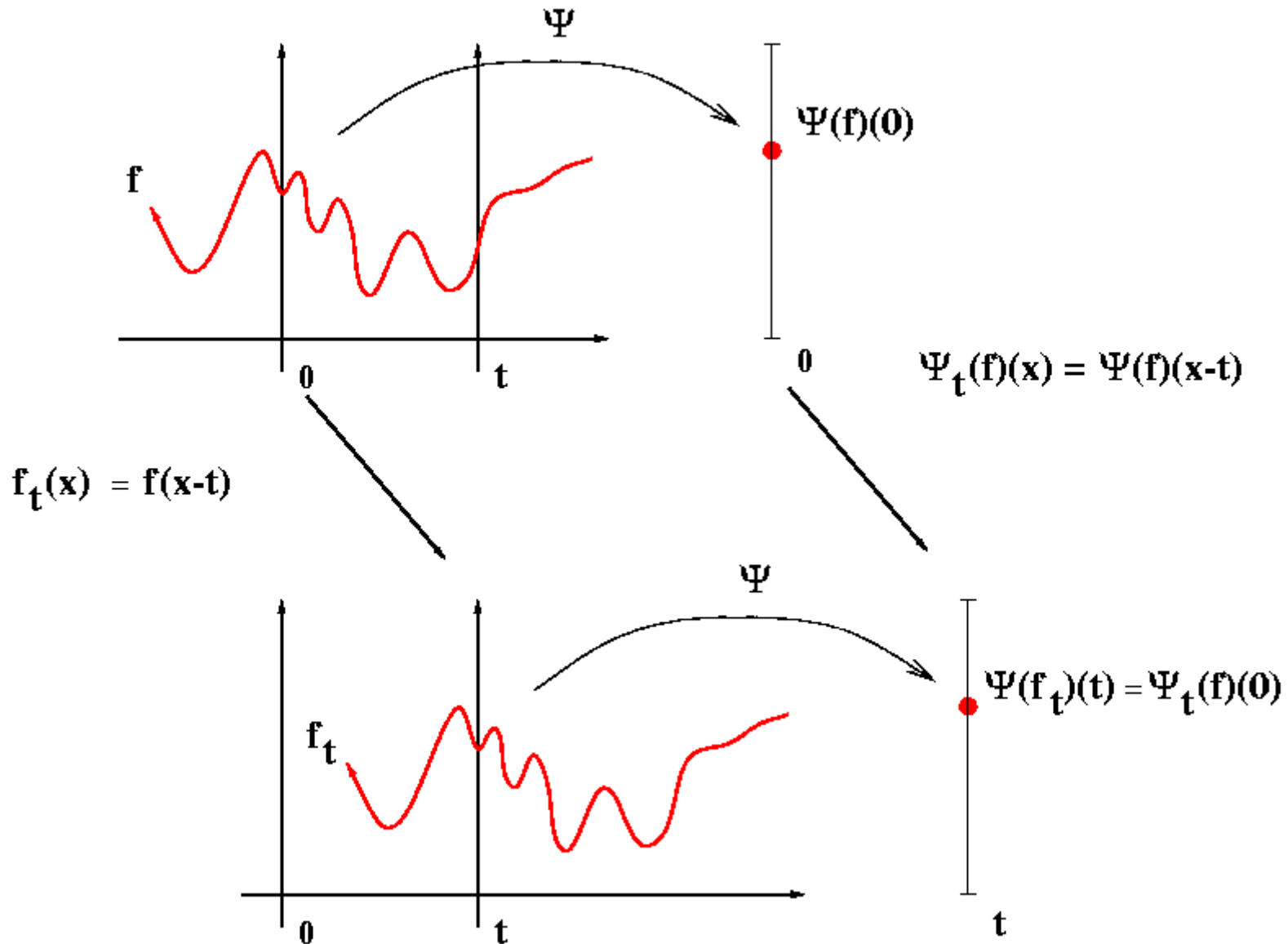
# Introduction

- In the **binary** case, the family of W-operators is usually considered
- The family of **binary** W-operators has  $2^{2^{|W|}}$
- In the **gray-scale** case, the family of W-operators is also usually considered
- The family of **gray-scale** W-operators has  $l^m$   $|W|$
- In **ordinary** applications  $l=m=256$

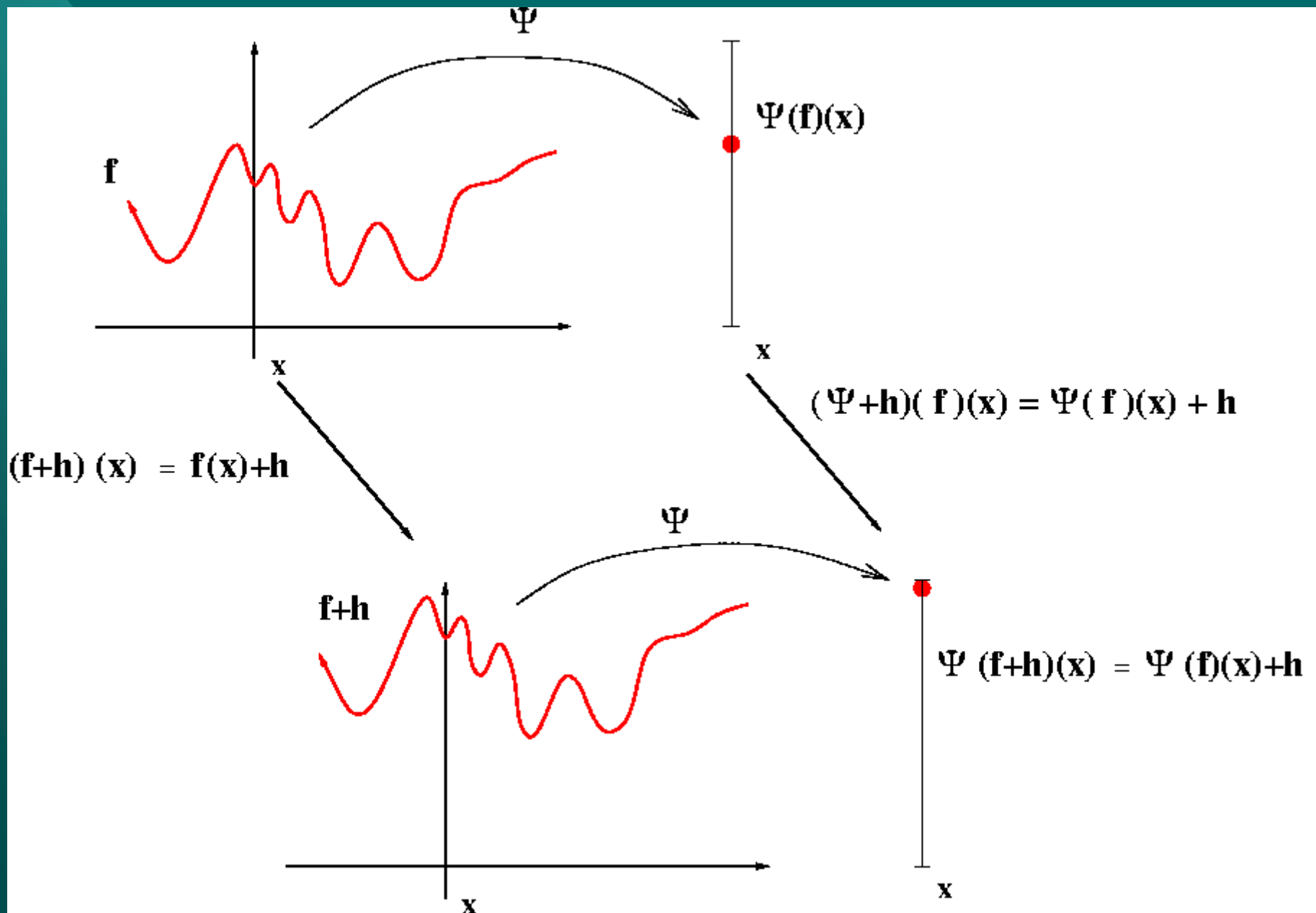
# Introduction

- The family of **Aperture operators** depends on a spatial window  **$W$**  and a gray-scale window  **$K=[-k,k]$**
- The **family** of aperture filters has  $|K|^{|K|^{|W|}}$
- The **complexity** of the optimization problem is controlled by  $|K|$  and  $|W|$
- The values of  **$k$**  and  **$|W|$**  depends on the problem:  $k=3, 5, 7, \dots$  and  $|W| = 9, 25, 49, \dots$

# Aperture Operators - Horizontal Translation Invariance

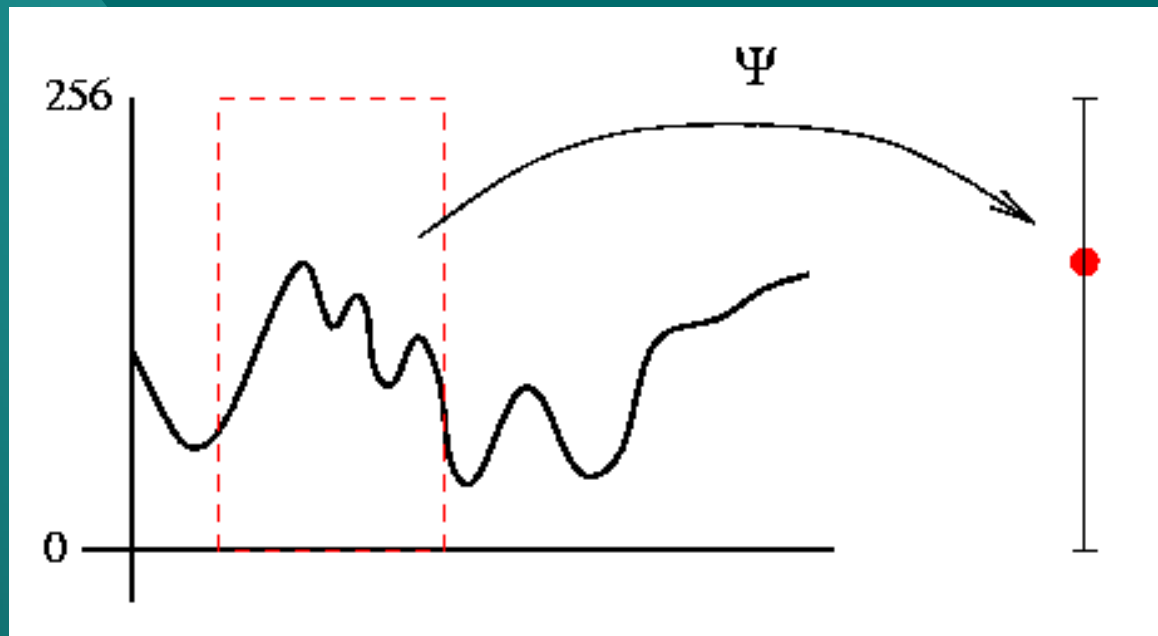


# Aperture Operators - Vertical Translation Invariance



# Aperture Operators

- Locally defined in  $W$

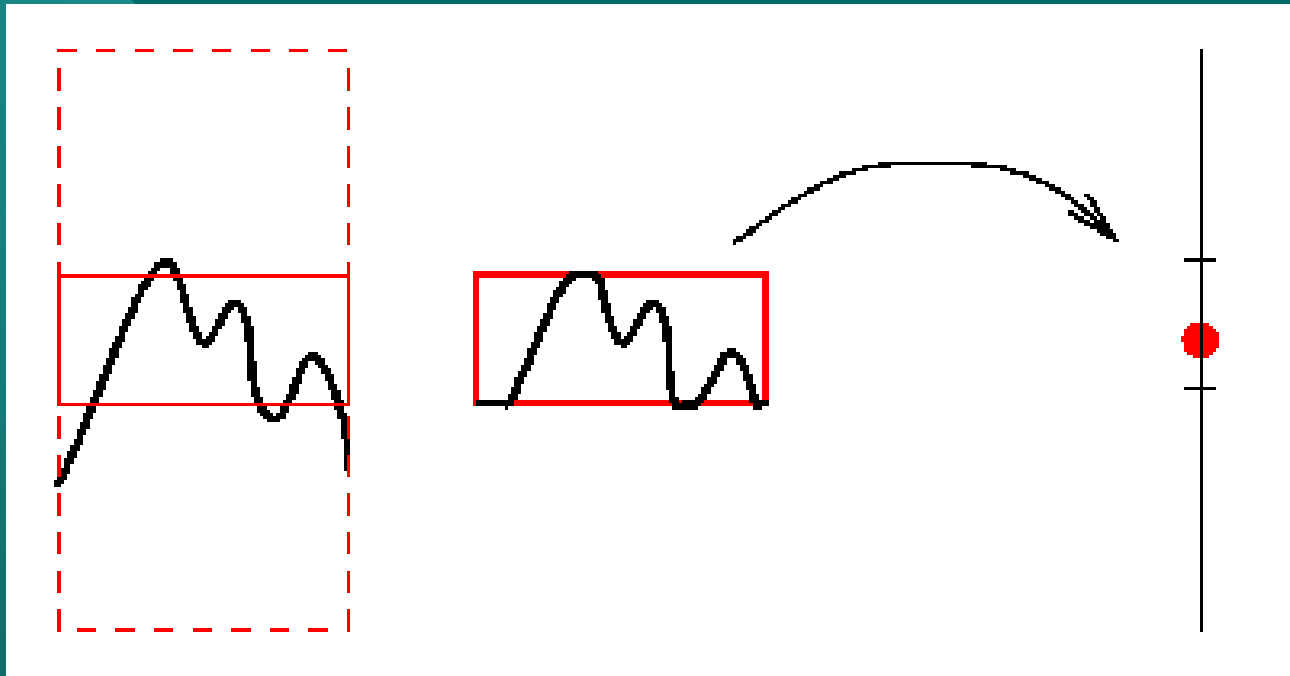


$$\Psi(f)(x) = \Psi(f / W_x)(x)$$



# Aperture Operators

- Locally defined in  $W$  and  $K$



$$(u / K_y)(z) = \wedge\{\vee\{-k, u(z) - y\}, k\}$$

# Aperture Operators

$\beta_\psi$

2	-2	1	2	2	2
1	-2	1	2	2	2
0	-2	1	2	2	2
-1	-2	1	1	1	1
-2	-2	-2	-2	-2	-2

-2	-1	0	1	2
----	----	---	---	---

$\psi$

$u(o)$

$\beta_\psi$

14	12	13	14	15	16
13	12	13	14	15	15
12	12	13	14	14	12
11	12	13	13	11	12
10	12	12	10	11	12
	10	11	12	13	14

=

14	10	11	12	13	14
13	10	11	12	13	14
12	10	11	12	13	14
11	10	11	12	13	14
10	10	11	12	13	14
	10	11	12	13	14

+

14	2	2	2	2	2
13	2	2	2	2	1
12	2	2	2	1	-2
11	2	2	1	-2	-2
10	2	1	-2	-2	-2
	10	11	12	13	14

# Aperture Operators

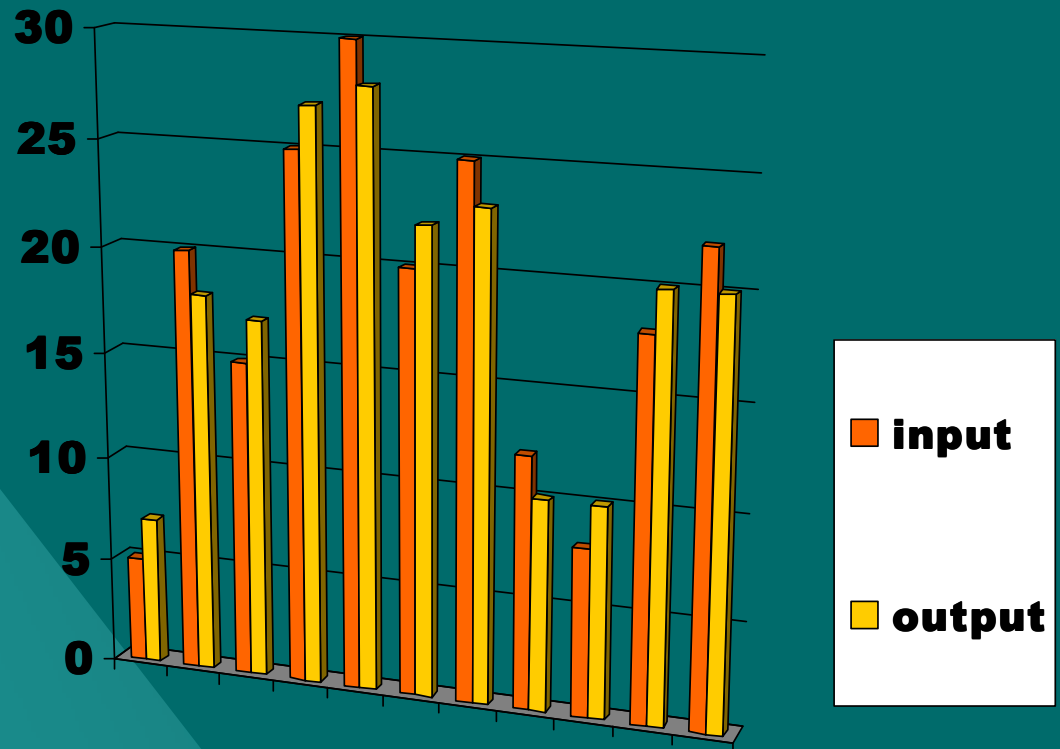
W



$$K = \{-2, -1, 0, 1, 2\}$$

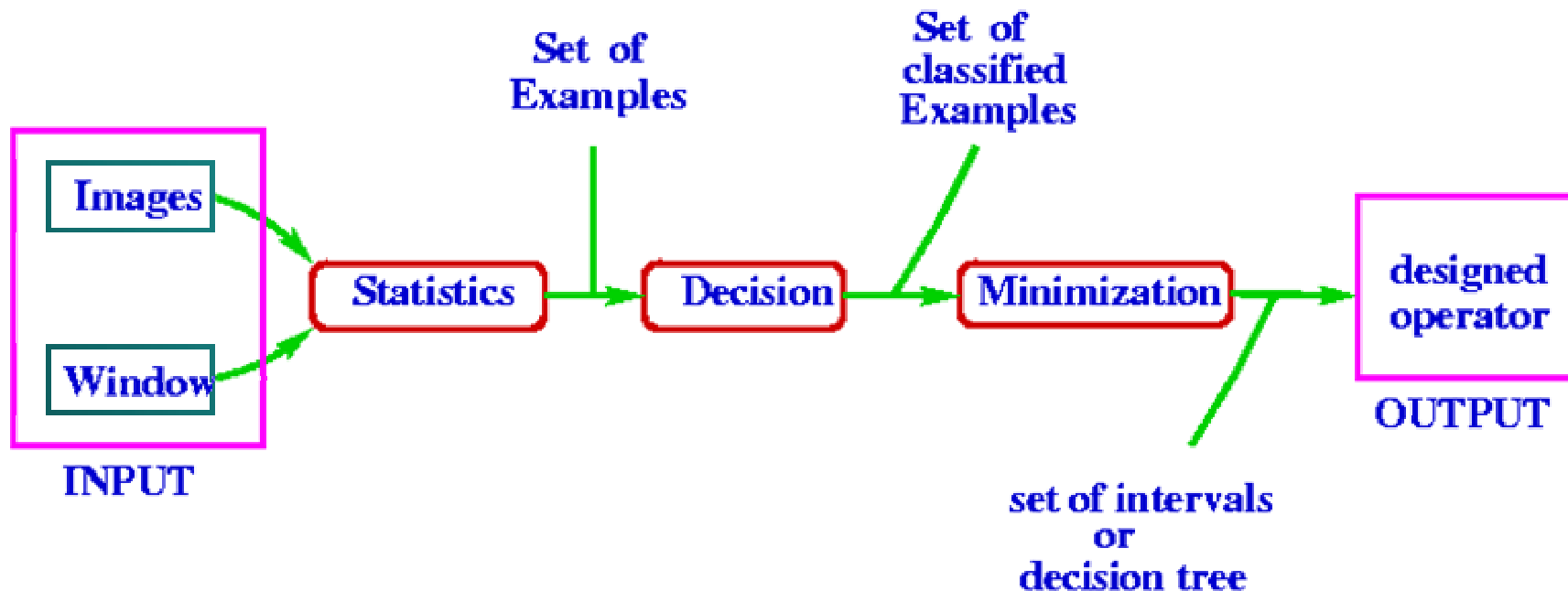
$\beta_\psi$

2	-2	1	2	2	2
1	-2	1	2	2	2
0	-2	1	2	2	2
-1	-2	1	1	1	1
-2	-2	-2	-2	-2	-2
	-2	-1	0	1	2



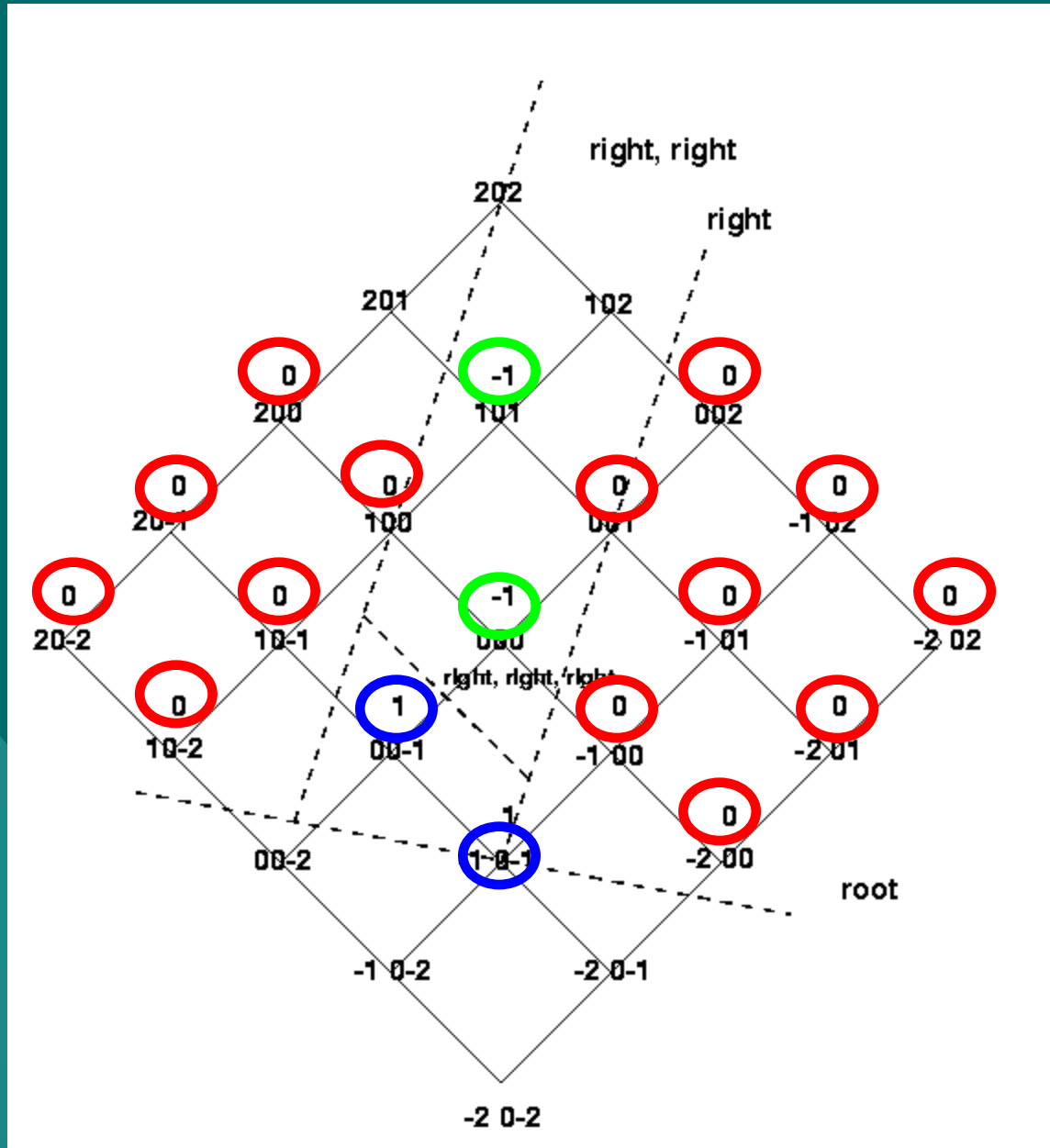
# Design of Aperture Operators

## Learning System



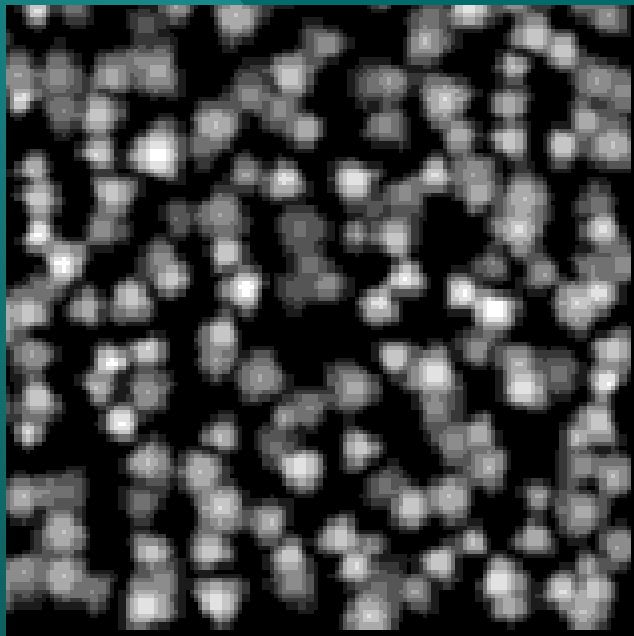
# Design of Aperture Operators

Lattice representation of the kernel of the operator

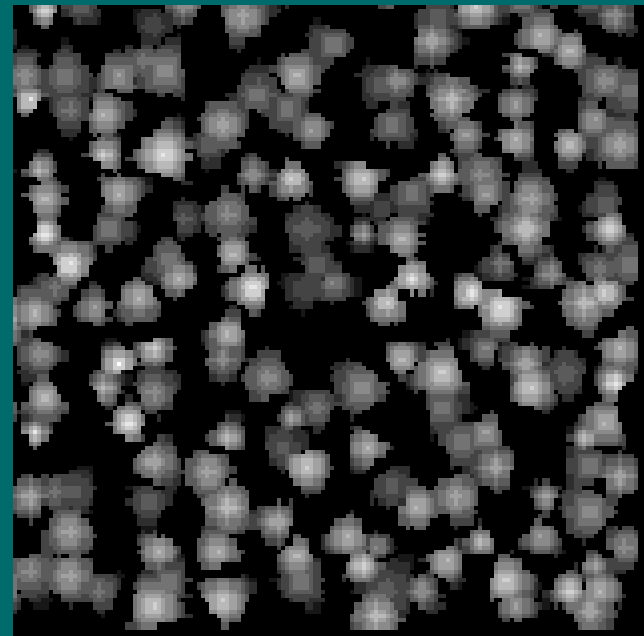


# Apertures for Deblurring

Observed

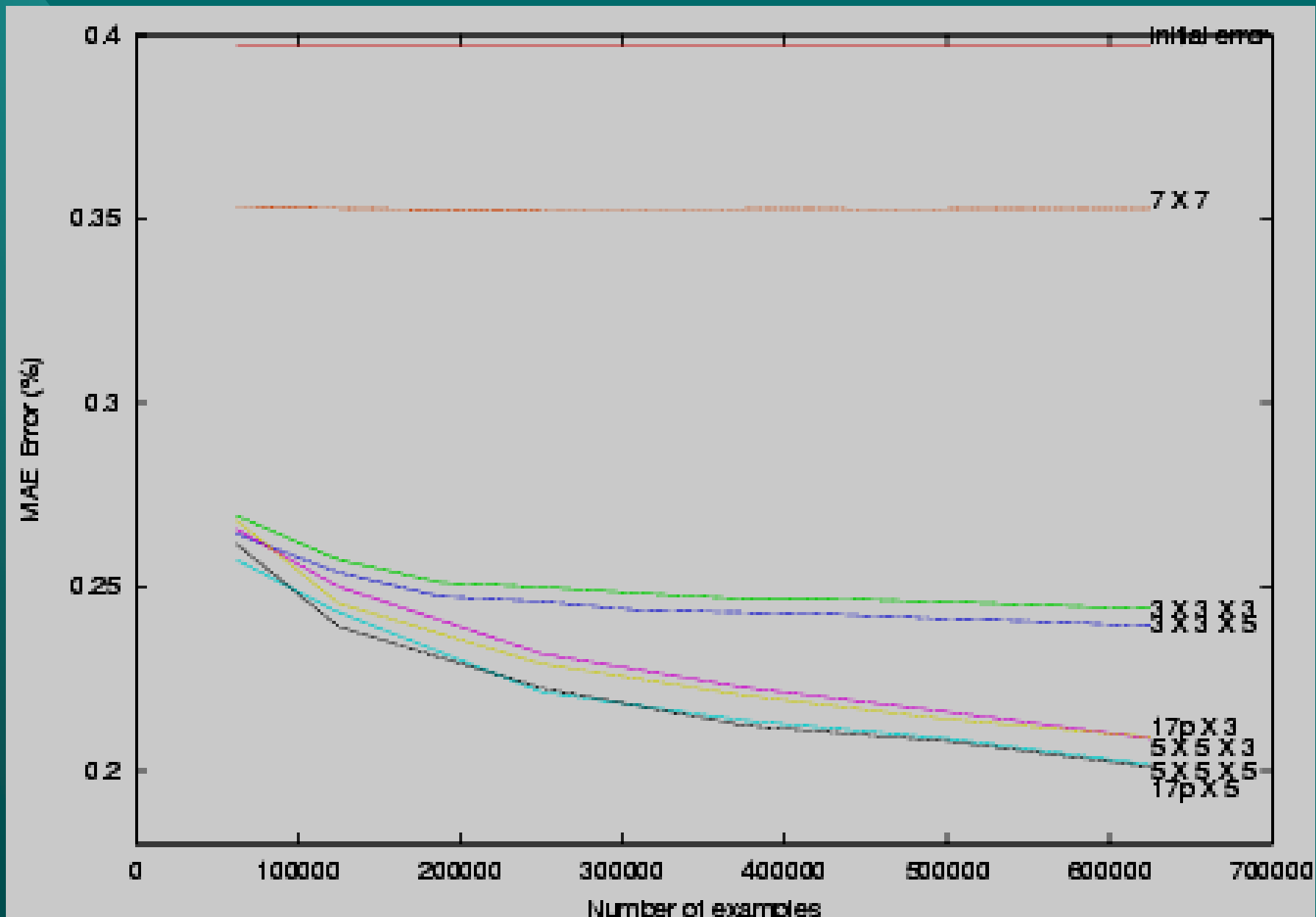


Ideal



These are part of the observed and ideal images (512x512)

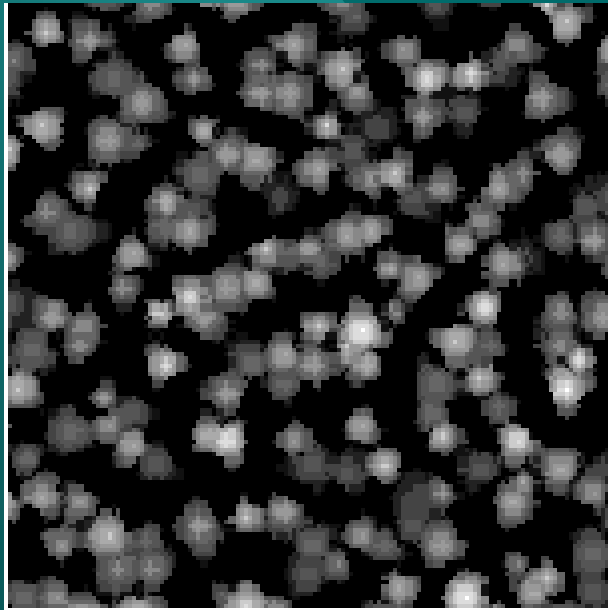
# MAE x Number of Examples



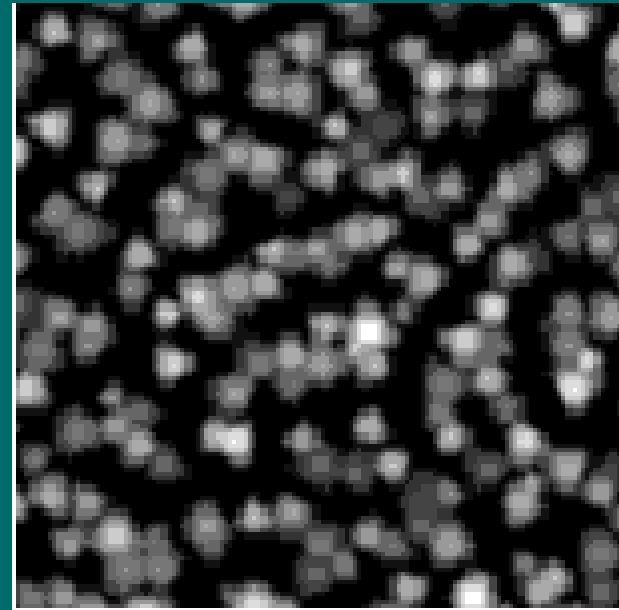
# Apertures for Deblurring

Deblurring - Aperture x Optimal linear

Aperture 17p x 5 x 5



Optimal linear 7x7





# Apertures for Deblurring

**CBERS simulation**

**SPOT**



**413x413**

# Apertures for Deblurring

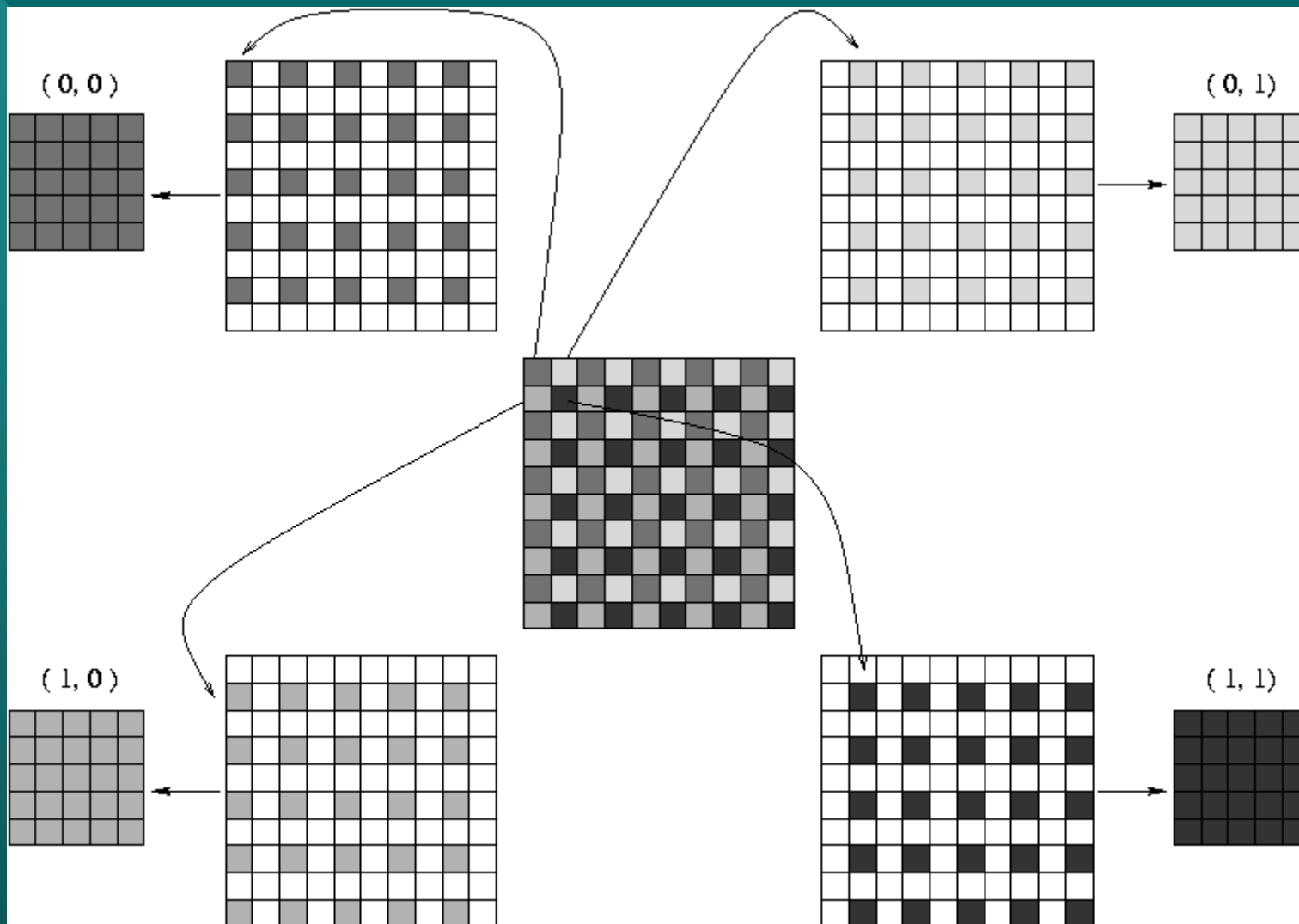
- Training with 50% of the image (points randomly chosen)
- Aperture result is visually slightly better

Aperture: 13 points x 15 x 21

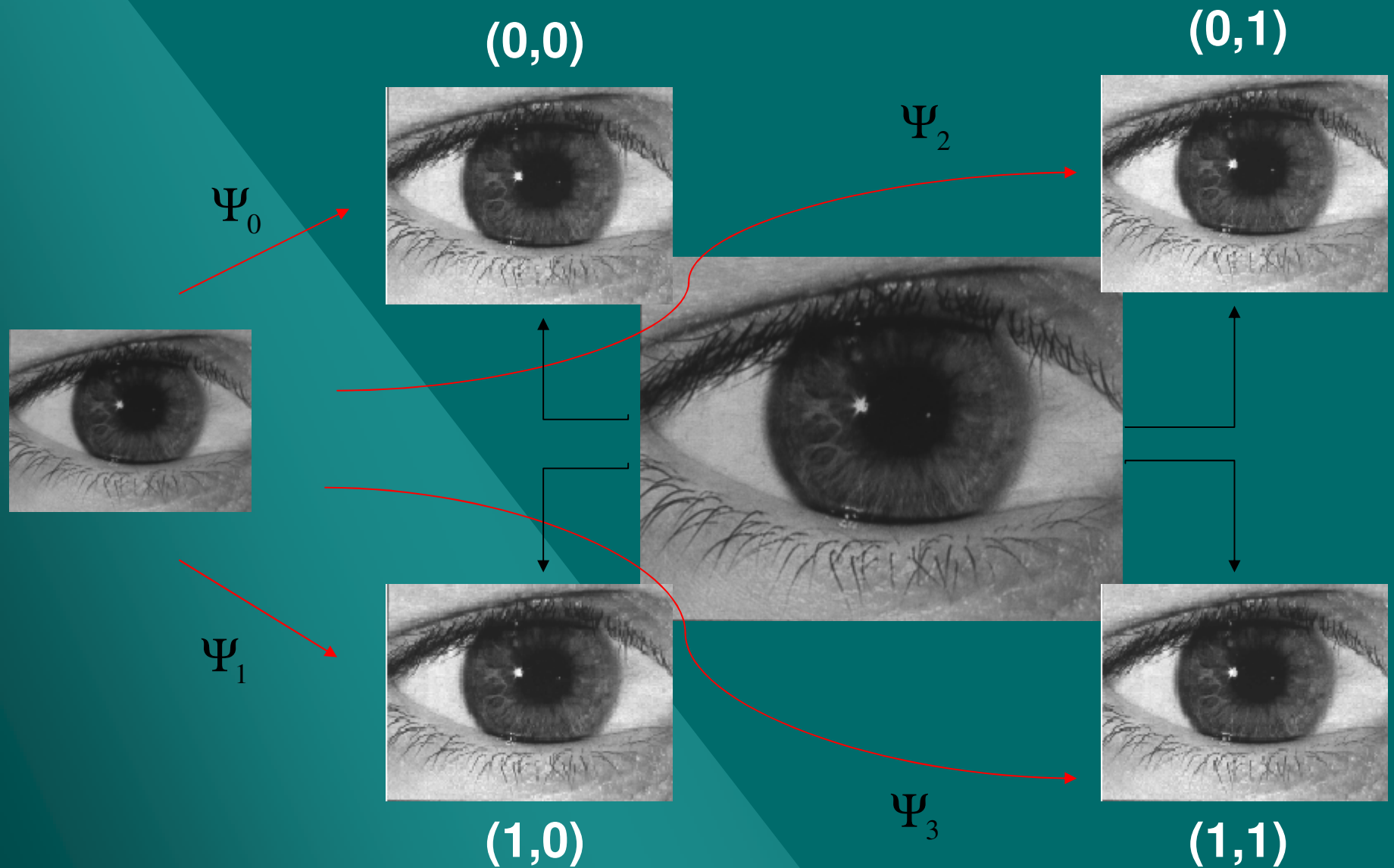
Optimal linear - same size



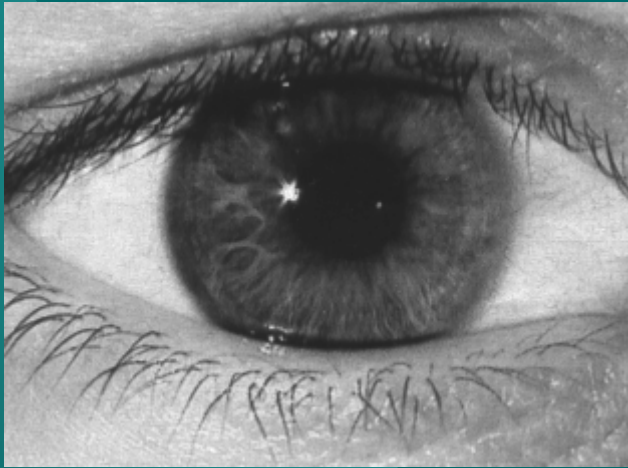
# Resolution Enhancement



# Resolution Enhancement



# Resolution Enhancement - Results



**Original**



**Aperture: 3x3x21x51**



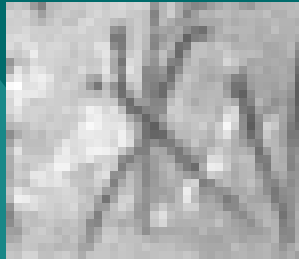
**Linear**



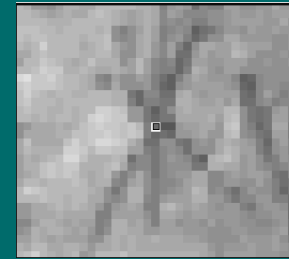
**Bilinear**

# Resolution Enhancement - Results

## Zoom



Original



Aperture: 3x3x21x51



Linear

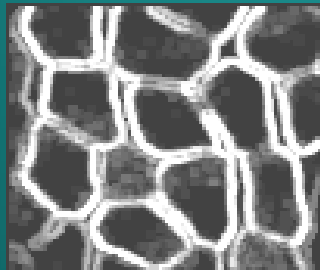


Bilinear

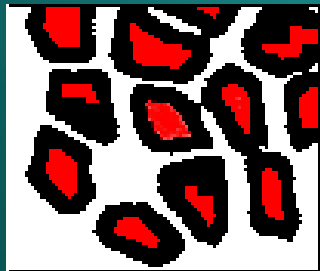
# Beucher-Meyer Paradigm

A powerful segmentation method to find the borders of specified objects in an image.

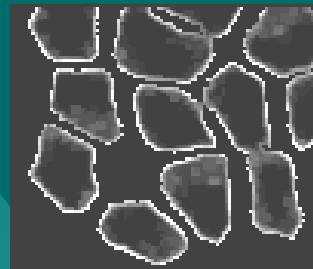
**Gradient**



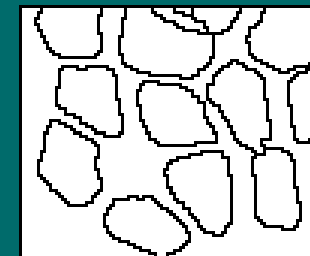
**Markers**



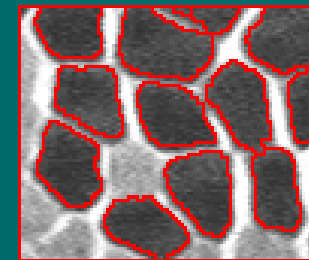
**Filtered Gradient**



**Watershed lines**



**Composed Image**



# Markers for Segmentation

Some images are manually segmented and used to train an operator

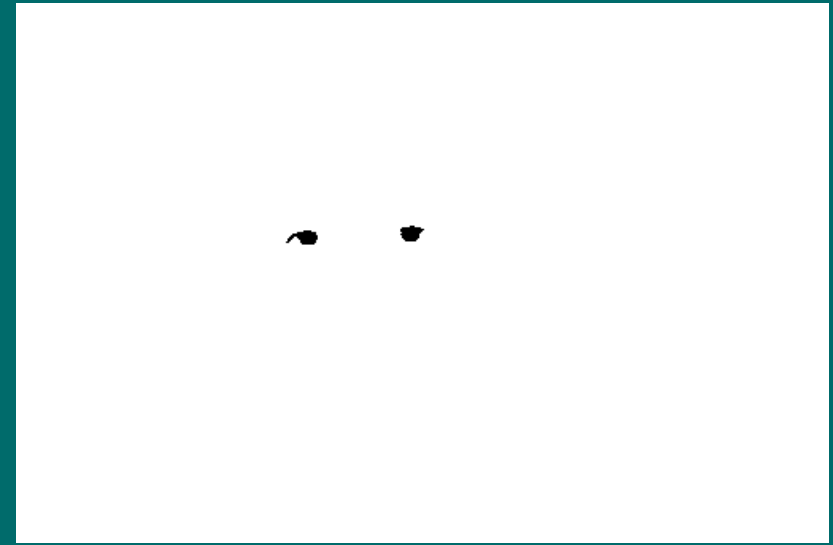
Observed



Ideal



512x342



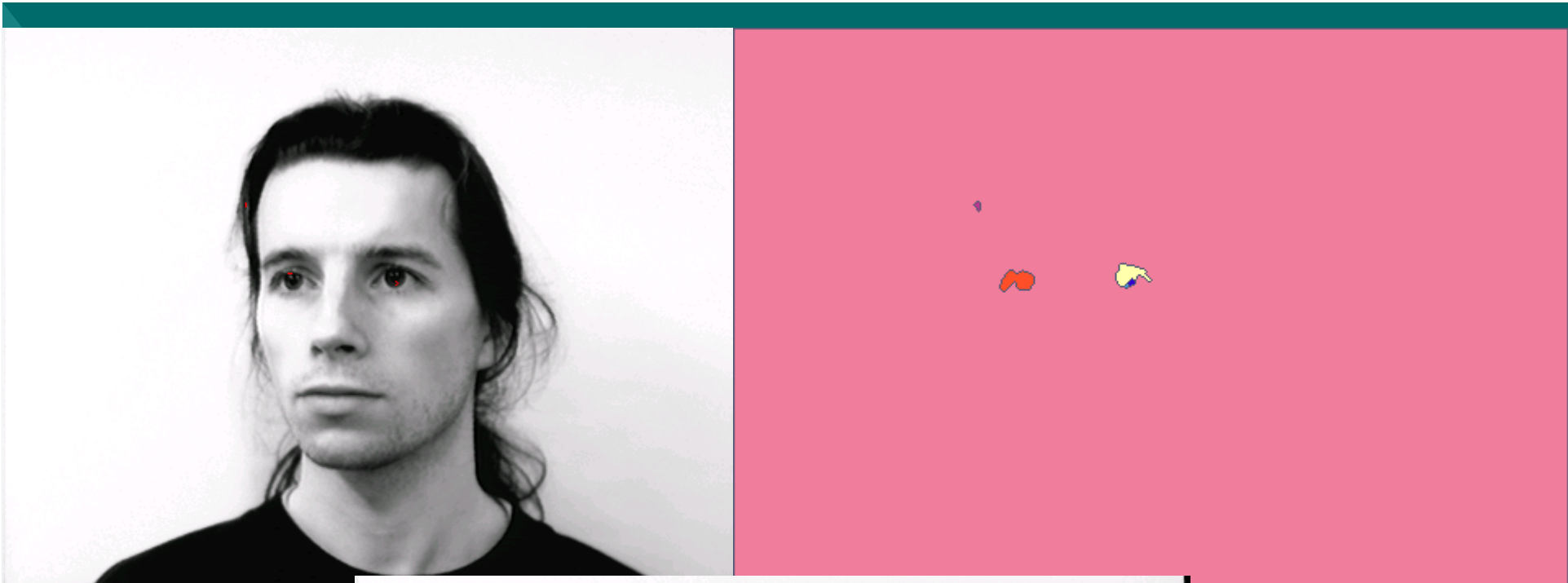
aperture: 3x5x21x21

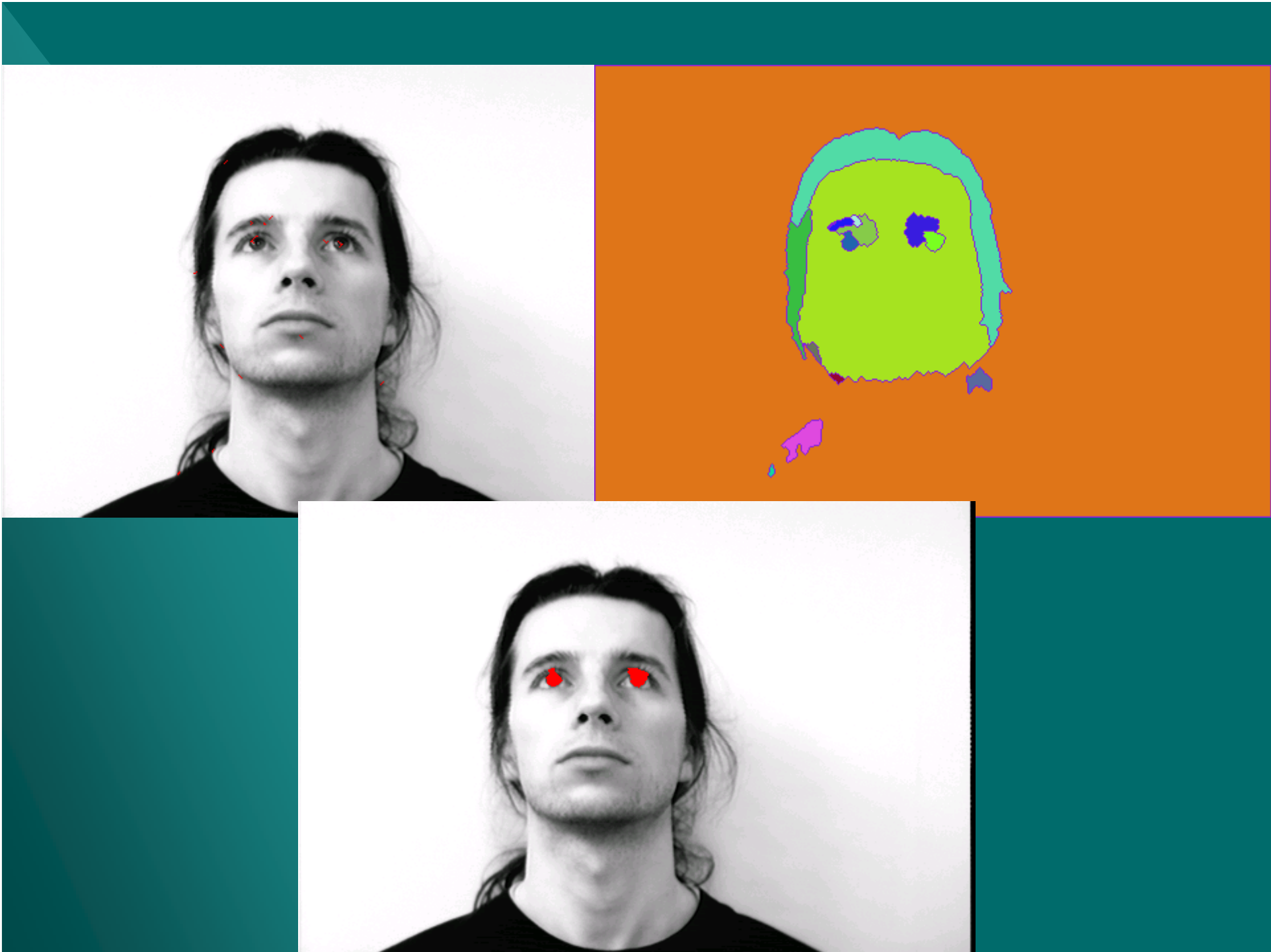


# Markers for Segmentation Results

- One image to train the operator
- Nine images to test the designed operator
- Perfect segmentation: 6
- Missing one eye: 1
- Missing both eyes: 2







# Segmenting a tennis racket

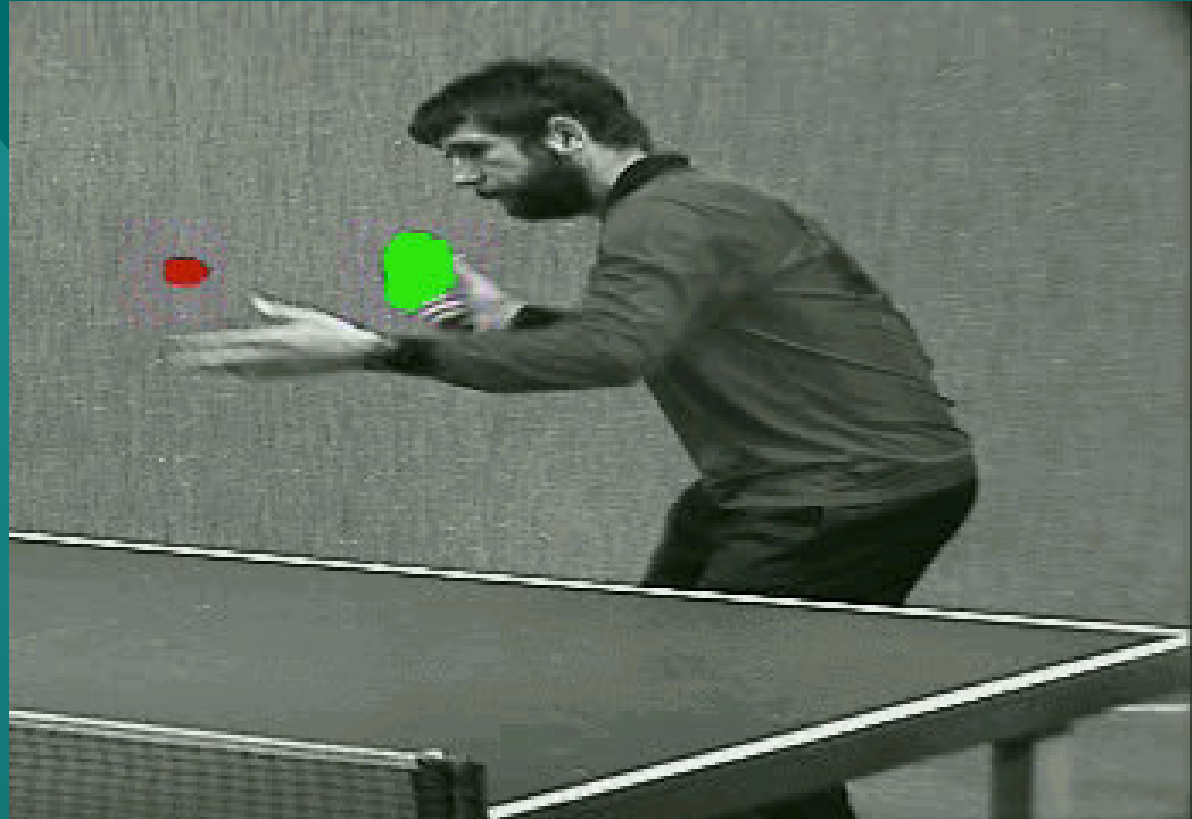
**Observed**



**Ideal**



# Some result images



**Experiments done by Franklin C. Flores** - [fcflores@ime.usp.br](mailto:fcflores@ime.usp.br)

<http://www.vision.ime.usp.br/demos.html>

# Some result images



**Experiments done by Franklin C. Flores** - [fcflores@ime.usp.br](mailto:fcflores@ime.usp.br)

<http://www.vision.ime.usp.br/demos.html>