# Simulator for gene expression networks

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## Outline

- Introduction
- Finite Chain Dynamical Systems (FCDS)
- A simulator for FCDS
- Cell cycle control
- Conclusion

## Introduction

## Gene Expression Network

- A system of genes that control cellular phenomena. For example: cell cycle.
- A gene send messages to other genes
- A set of genes may activate or inactivate other genes.
- Expression levels change in time

#### Gene Expression Network



## Genetic Systems

- Gene networks are dynamical systems
- The architecture and dynamics of these systems are unknown
- Microarrays permit to observe states of the systems

## System Evolution

• Trajectory



## Gene Systems identification

- System architecture and dynamics theoretically can be estimated purely from microarray data
- The amount of necessary data is not feasible
- Use of disciplinary (all kinds of information) knowledge together with microarray data is a more realistic approach

## Knowledge representation

- Disciplinary knowledge is condensed in models designed heuristically through simulations
- Systems identified from microarrays should have some degree of consistency with the heuristic models.

## Chain Dynamical System

#### Diagram of a chain dynamical system



### Mathematical Formulation

 $\mathbf{x}[i], \mathbf{u}[i] \in \mathcal{L}^n$   $\mathbf{y}[i] \in \mathcal{L}^m$ 

 $\Phi_i: \mathcal{L}^{2(N+1)n} \to \mathcal{L}^n \qquad \qquad \Psi_i: \mathcal{L}^{2(N+1)n} \to \mathcal{L}^m$ 

 $\mathbf{x}[i+1] = \Phi_i(\mathbf{x}[i-N], \dots, \mathbf{x}[i], \mathbf{u}[i-N], \dots, \mathbf{u}[i])$ 

 $\mathbf{y}[i] = \Psi_i(\mathbf{x}[i-N], \dots, \mathbf{x}[i], \mathbf{u}[i-N], \dots, \mathbf{u}[i]),$ 

### Example



 $\phi_1(\mathbf{x}[i-5], \mathbf{x}[i-4], \mathbf{x}[i-3], \mathbf{x}[i-2], \mathbf{x}[i-1], \mathbf{x}[i]) = \overline{x}_1[i-3] \cdot \overline{x}_1[i-2] \cdot \overline{x}_1[i-1] \cdot \overline{x}_2[i-5] \cdot \overline{x}_2[i-3] \cdot \overline{x}_2[i-1]$ 

 $\phi_2(\mathbf{x}[i-5], \mathbf{x}[i-4], \mathbf{x}[i-3], \mathbf{x}[i-2], \mathbf{x}[i-1], \mathbf{x}[i]) = \overline{x}_1[i-4] \cdot \overline{x}_2[i-5] \cdot \overline{x}_2[i-4] \cdot \overline{x}_2[i-3] \cdot \overline{x}_2[i-2] \cdot \overline{x}_2[i-1] \cdot \overline{x}_2[i-1] \cdot \overline{x}_2[i-2] \cdot \overline{x}_2[i-1] \cdot \overline{x}_2[i-2] \cdot \overline{x}_2[i-1] \cdot \overline{x}_2[i-2] \cdot$ 

Why chain dynamical systems?

- Discrete systems are enough to represent phenomena of interest
- Quite general non linear systems can be represented
- Learning techniques available are appropriate to include prior knowledge

A simulator for chain dynamical systems

#### Simulator Architecture



#### **Functions Representation**





#### System Description

## Cell Cycle Control

## **Biological Model**

- Cell cycle control by Fibroblast Growth Factor 2 (FGF2) and Adrenocorticotropic Hormone (ACTH) in the Y1 adrenocortical cell line
- FGF2 has long been considered a candidate for participating in cell cycle control, but its molecular mechanisms remain obscure

## Mitogenic response in G0/G1 cell cycle to FGF2:

- Rapid and transient activation of extra cellular signal-regulated kinases
- Transcription activation of c-fos, c-jun and c-myc genes
- Induction of c-Fos and c-Myc proteins and cyclin D1 protein
- DNA synthesis stimulation

## Anti-mitogenic response in G0/G1 cell cycle to ACTH:

- Blocks FGF2 mitogenic response
- Keeps ERK activation and c-Fos and cyclin D1 induction on
- Down regulates the levels of the c-Myc protein
- Down regulates the active form of Akt/PKB enzyme

#### A model for the FGF2/ACTH influence on cell cycle



#### Model Formalization

Element	Rule
FGF2R[i]	receives external signal
$\operatorname{ACTHR}[i]$	receives external signal
$\mathrm{ERK1/2[}i]$	$FGF2R[i-1] \cdot anti-ERK[i-1]$
PI3K[i]	$FGF2R[i-1] \cdot anti-PI3K[i-1]$
PKA[i]	$ACTHR[i-1] \cdot anti-PKA[i-1]$
$\operatorname{Akt}[i]$	$(\operatorname{PI3K}[i-2] + \operatorname{PI3K}[i-1]) \cdot \overline{\operatorname{PKA}[i-2]} \cdot \overline{\operatorname{PKA}[i-1]}$
c-fos[i]	$\mathrm{ERK1/2[}i\!-\!3]+\mathrm{ERK1/2[}i\!-\!2]+\mathrm{PKA[}i\!-\!3]+\mathrm{PKA[}i\!-\!2]$
c-jun[ $i$ ]	$\mathrm{ERK1/2[}i\!-\!3]+\mathrm{ERK1/2[}i\!-\!2]+\mathrm{PKA[}i\!-\!3]+\mathrm{PKA[}i\!-\!2]$
c-myc[ $i$ ]	$\overline{\mathrm{PKA}[i-2]} \cdot \overline{\mathrm{PKA}[i-1]} \cdot (\mathrm{ERK1}/2[i-3] + \mathrm{ERK1}/2[i-2])$
$\mathrm{D1}[i]$	$\operatorname{c-fos}[i\!-\!1]\cdot\operatorname{c-jun}[i\!-\!1]\cdot(\operatorname{PI3K}[i\!-\!4]-\operatorname{PI3K}[i\!-\!3])$
$\operatorname{Id2}[i]$	c-myc[ $i$ -1]
p27kip1[i]	$\overline{\operatorname{Akt}[i-2]}$
$\operatorname{CDK}[i]$	$D1[i-1] \cdot \overline{p27 \text{kip1}[i-1]}$
$\operatorname{Rb}[i]$	$\mathrm{CDK}[i\!-\!1]\cdot\mathrm{Id}2[i\!-\!2]$

#### Effect of one pulse of FGF2



#### Effect of one pulse of ACTH



## Conclusion

- We proposed chain dynamical systems as a model for studying genetic networks,
- presented the architecture of a chain dynamical system simulator,
- proposed a model for a subsystem of genes and proteins that control a cell cycle,
- simulated the proposed model
- The next step of this research is to incorporate microarray information.